

But we want  $n_0^\alpha$  to be flipped

$$0 = \int_{\Sigma_1} J^\alpha n_{1\alpha} \sqrt{h} d^3y + \int_{\Sigma_0} J^\alpha (-n_{0\alpha}) \sqrt{h} d^3y$$

$$\therefore \int_{\Sigma_0} J^\alpha n_{0\alpha} \sqrt{h} d^3y = \int_{\Sigma_1} J^\alpha n_{1\alpha} \sqrt{h} d^3y$$

$$\therefore Q = \int_{\Sigma} J^\alpha n_{\alpha} \sqrt{h} d^3y = \text{conserved}$$

as  $Q$  is indep. of choice of  $\Sigma$

By  $\nabla_\alpha T^{\alpha\beta} = 0$

there is no such conservation from this Eqn

L-11

Intrinsic & Extrinsic Geometry.

①

In spacetime we have metric  $g_{\alpha\beta}$ , we have connection  $\Gamma$

The curvature comes from then  $R^{\alpha}_{\beta\gamma\delta}$

②

In  $H-S y^a$

we have  $h_{ab}$ , we have connection  $\Gamma^a_{bc}$

from this we get intrinsic curv. of H-S

$R^a_{bcd}$

③

Relation B/w Both  $\Gamma$   
Relation B/w Spacetime  $R$  & intrinsic  $R$

Spacetime (Bulk) Curvature = Intrinsic Curvature + Extrinsic Curvature

Evaluation H.S

④

→ Gauss Codazzi

④

$R^a_{bcd}$  is the geometry of the H.S

⑤

In Book everything is done in covariant form i.e.

We don't want to know relationship B/w  $x^\alpha$  &  $y^a$

though there will be some relationship but I don't want to know what it is

(6) In the lecture I will assume some relationship by taking suitable coordinate system.

(7) Assuming H.S. is spacelike.

In Null Case: Relationship B/w Extrinsic & Intrinsic Curvature is subtle.

(8) To work in the neighborhood of the H.S. choose Gaussian Normal coordinates  $(x^a)$

$\therefore$  The spacetime coordinate system would be fixed.

But ~~take~~ there is freedom to choose intrinsic coordinates.

i.e. Everything is covariant w.r.t.  $y^a \rightarrow y^a$ .

Intrinsic Covariant Derivative

Defined on H.S. with intrinsic connection

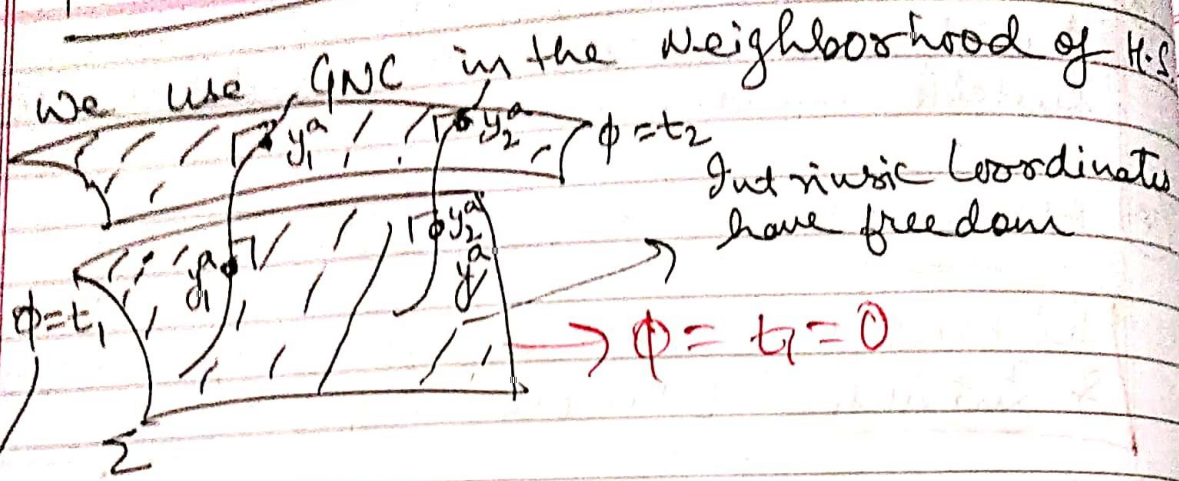
~~$\nabla_a$~~   $\equiv$  Intrinsic Covariant Derivative.

When  ~~$\nabla_a h_{bc}$~~   $h_{bc} = 0$  then we say connection is compatible with intrinsic metric on H.S.

$$h_{bc|a} = 0 \quad \equiv \quad \nabla_a g_{\beta\gamma} = 0$$

# Gaussian Normal Coord. $(x^\alpha)$

(10)



⇒ H.S. ~~where~~ proper time fixed.

⇒ Assuming  $y^a$  remains same along the curve just proper time changes.

⇒ Assuming all curves are H.S.  $\perp$ .

⇒ Not compulsory for curves to be geodesic

GNC :  $x^\alpha$  :  $x^0 = t = \text{proper time}$   
 $x^a = y^a$  → parameters

(11) GNC turns out to be really beneficial locally around H.S. when I am interested all in H.S.

(2) Metric Spacetime in GNC

$$ds^2 = g_{\alpha\beta} dx^\alpha dx^\beta = dt^2 - g_{ab}(t, x^a) dx^a dx^b$$

# Metric from Analysis

classmate

Date

Page

137

⇒ Moving just along curves  $dx^a = 0$  & only proper time is changing which is also evident from metric

$$ds^2 = dt^2 - g_{ab} dx^a dx^b$$

$$\underline{ds^2 = dt^2} \quad \text{along the curves} \quad dx^a = 0$$

⇒ But by above argument we can still have  $dt dx^a$  terms in the metric

$$g_{\alpha\beta} = h_{\alpha\beta} + U_\alpha U_\beta$$

comoving frame

↳ originated in Minkowski & in flat  $U_\alpha \perp h_{\alpha\beta}$   
But as they are tensors  $g_{\alpha\beta} = h_{\alpha\beta} + U_\alpha U_\beta$

though  $U_\alpha$  is  $\perp$  or not to H-S.  
This is valid

Similarly

$$g_{\alpha\beta} = h_{\alpha\beta} + \epsilon n_\alpha n_\beta$$

↳ in Mink spacetime as  $U_\alpha \perp h_{\alpha\beta}$  &  $U_\alpha = n_\alpha$

$$\therefore g_{\alpha\beta} = h_{\alpha\beta} + \epsilon n_\alpha n_\beta \text{ in } \underline{\text{General}}$$

But now in this situation

$U_\alpha$  is  $\perp$  to H-S in GNC coord.

$$g_{\alpha\beta} = h_{\alpha\beta} + U_\alpha U_\beta \text{ where } U_\alpha \perp h_{\alpha\beta}$$

$$\therefore g_{\alpha\beta} = \left( \begin{matrix} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \end{matrix} \right) = U_\alpha U_\beta + h_{\alpha\beta}$$

as  $U_\alpha \perp h_{\alpha\beta}$   
 $U_\alpha = (a, 0, 0, 0)$

$\Rightarrow$  Only dt coeff in  $ds^2$   
 all others dt  $dx^a = 0$

(13) if  $t=0$  on the H.S.  $ds^2 = dt^2 - g_{ab} dx^a dx^b$   
 $g_{ab}(x^0=0, x^a) = h_{ab} \quad g_{ab}(t, x^a)$

Spacetime metric = Induced metric

if  $t = t_2 \neq 0$  other ~~H.S.~~ H.S. considered  
 $g_{ab}(x^0=t_2, x^a)$

But on our H.S.  $t=0$   
 $g_{ab} = h_{ab}$

because  $ds^2 = g_{ab}(t, x^a) dx^a dx^b$   
 H.S.  $t=0 = g_{ab}(t=0, x^a) dx^a dx^b$

~~But  $h_{ab}$  is dependent on time  $(t, y^a)$~~

But By Def:  $ds^2 = h_{ab} dy^a dy^b$   
 H.S.  $t=0$  But  $y^a = x^a$

$\therefore g_{ab}(t=0, x^a) = h_{ab}$

2. Does this coordinate system work if there is singularity?

(14) QNC coordinates help us to get metric on H.S. which is easy.

(15) We can also take QNC in 2D H.S.

Here 4D  $\rightarrow$  3D

But also 3D  $\rightarrow$  2D

(16) Using QNC calculation  $\Gamma$ ,  $R^a_{bcd}$

(17) 
$$g_{\alpha\beta} = \begin{pmatrix} 1 & 0 \\ 0 & -g_{ab} \end{pmatrix}$$

$$g^{\alpha\beta} = \begin{pmatrix} 1 & 0 \\ 0 & -g^{ab} \end{pmatrix} \quad \left\{ \text{Proof} \right\}$$

(18) 
$$\Gamma^{\alpha}_{\beta\gamma} = \frac{g^{\alpha\mu}}{2} \left( -\partial_{\mu} g_{\beta\gamma} + \partial_{\beta} g_{\mu\gamma} + \partial_{\gamma} g_{\mu\beta} \right)$$

$\alpha = 0, 1, 2, 3$

calculating it  $\Gamma^0_{\alpha 0} = 0$   $\Gamma^{\alpha}_{00} = 0$

$$\Gamma^0_{ab} = \frac{\partial_0 g_{ab}}{2}$$

$$\Gamma^a_{tb} = \frac{g^{am}}{2} \partial_t g_{mb}$$

$$\Gamma^a_{bc} = \frac{g^{am}}{2} \left( -\partial_m g_{bc} + \partial_b g_{cm} + \partial_c g_{mb} \right)$$

Valid anywhere  
~~anywhere~~  
 wrong the

(19)  $t=0$  making on the H-S.  $\phi=0$

~~${}^4\Gamma_{ab}^0 = k_{ab} = \frac{\partial_0 g_{ab}}{2} \Big|_{t=0}$~~   ~~$\Rightarrow \frac{\partial_0 g_{ab}}{2}$~~

Intrinsic Curvature  $t=0$

$$\begin{aligned} {}^4\Gamma_{ob}^a &= \frac{1}{2} g_{mb}^{\text{at } t=0} \partial_0 g_{mb} \Big|_{t=0} \\ &= \frac{h_{am}}{2} \partial_0 g_{mb} \Big|_{t=0} \\ &= h_{am} k_{mb} \\ &= \underline{k_b^a} \end{aligned}$$

is  $k_{ab}$  dependent on time?

~~${}^4\Gamma_{bc}^a = \frac{h_{am}}{2} (-\partial_m g_{bc}) \Big|_{t=0} + \partial_b g_{cm} \Big|_{t=0} + \partial_c g_{mb} \Big|_{t=0}$~~

See (35) (36)  $k_{ab}$  is scalar under  $y \rightarrow y'$

~~${}^4\Gamma_{bc}^a \equiv \partial \Gamma_{bc}^a$~~

(20)  $\Gamma$  are not tensors in spacetime coord

~~Proof~~  ${}^4\Gamma$  are not tensors in intrinsic coord

But  ${}^4\Gamma_{ab}^t$  are tensors in intrinsic coord  $y^a \rightarrow y'^a$

~~Proof?~~  $\therefore$  as  ${}^4\Gamma_{ab}^0 = k_{ab}$

$k_{ab}$  scalar w.r.t  $y^a \rightarrow y'^a$ ;  $k_{ab}$  is 3 tensor under  $y^a \rightarrow y'^a$



21) By using the Tangent vectors we can promote 3-tensor  $\rightarrow$  4-tensors

we can also pullback from 4-tensor  $\rightarrow$  3-tensor

$\therefore K_{ab}$  can also be defined as 4-tensor  
 $\therefore$  there is one-one correspondence b/w 4-T  $\rightarrow$  3-T.

22) Here in this GNC specified coord. system we can't prove

$K_{ab}$  as Tensors under  $y^a \rightarrow y'^a$

From Covariant, we can prove this.

23) AS  ${}^4T_{ab} = \frac{2}{2} \partial_0 g_{ab} \Big|_{t=0} = K_{ab}$  (Symm)

$\therefore {}^4T_{ab}, K_{ab}$  is symm

*basis vectors lie tangent*

$K_{ab}$  is Symm from Covariant approach?

$(\nabla_{\beta} \epsilon^{\alpha}) = c^{\beta}_{\alpha} \nabla_{\beta} \epsilon^{\alpha}$

24) On  $\Sigma$   $\phi = 0$  H.S. Why Not Tensorial on  $\Sigma$ ?

~~As  $R_{tabc}$  is not tensorial on  $\Sigma$~~

~~As  $R_{tabc}$  is not tensorial on  $\Sigma$~~

$R_{tabc} = -\frac{1}{2} \partial_t g_{ab} \Big|_{t=0} + K_{am} K^m_b$

3) Compare with from  $\Gamma$  terms

${}^4R_{tabc} = K_{able} - K_{ac}lb$  ①

How do I know  $K_{able}$  is Tensorial on  $\Sigma$ ?

See 135 19 43

Spatial Comp. of Bulk Curvature On HS.  $\uparrow$  Extrinsic Curv  $\uparrow$  Curya  $\uparrow$  Date Page

(9)  ${}^4R_{abcd} = {}^3R_{abcd} + K_{ac}K_{bd} - K_{ad}K_{bc}$

Compare with 3.29  $\downarrow$  Intrinsic Riemann Tensor

(1) & (2) are Tensorial  $\epsilon_{gh}$  on  $\Sigma$

(1) & (3) are called Gauss Codazzi  $\epsilon_{gh}$

(25) (1) & (2) has one time Derivative of  $g_{ab}$

$K_{ab/c} \rightarrow$  spatial

$$K_{ab} = \frac{\partial_0 g_{ab}}{2} \Big|_{t=0}$$

But (3) has 2 time Derivative of  $g_{ab}$

(26)  $\rightarrow$  Useful in Initial Value Problem

(26) Extrinsic Curvature tells Bending of submanifold embedded in  $4D$ .

(27) Till Now All these (1) & (2) & (3)  $\epsilon_{gh}$  are valid only in qnc

$\rightarrow$  (1) & (3) are Covariant under  $y^a \rightarrow y'^a$   
we will see that (1) (2) (3) are covariant  $x^i \rightarrow x'^i$  but not under  $x^i \rightarrow x'^i$

28 Einstein Tensor on  $\Sigma$   $\phi = 0$

29  ${}^4G_{tt} = \frac{1}{2} ({}^3R - k^{ab}k_{ab} + k^2)$

30  ${}^4G_{ta} = k^{ab}{}_{|b} - k_{|a}$

$k = \text{Tr} k^a_b$   
 $= k^a_a$   
 $= h^{ab} k_{ab}$

${}^4G_{ab} = {}^3q_{ab} + \frac{\partial^2}{\partial t^2} g_{ab}(t=0)$

$- \frac{h_{ab}}{2} (k^{cd} \frac{\partial^2}{\partial t^2} g_{cb}(t=0)) - 2k_{ac}k^c_b$   
 $+ \frac{3}{2} h_{ab} (k^{cd} k_{cd}) + k k_{ab} - \frac{h_{ab} k^c_c}{2}$

Prove all this?

29 All  $q_{ij}$  are valid in GNC

But just sic coordinates were chosen Arbitrarily defined  
Only Ext. Coe spacetime coord. were fixed.

30 To turn all this 4D. covariant exp.  $x^\alpha \rightarrow x^{\alpha'}$

Reintroduce Basis vectors on H.S.

$(n^\alpha, e^\alpha_a)$

in GNC  $D_{\alpha'} n^\alpha \propto \partial_\alpha \phi$

$\phi = t = 0 \Rightarrow n_\alpha \stackrel{*}{=} (1, 0, 0, 0)$   
 $n^\alpha \stackrel{*}{=} (1, 0, 0, 0)$

Normalized  $\delta_i$

in QNC

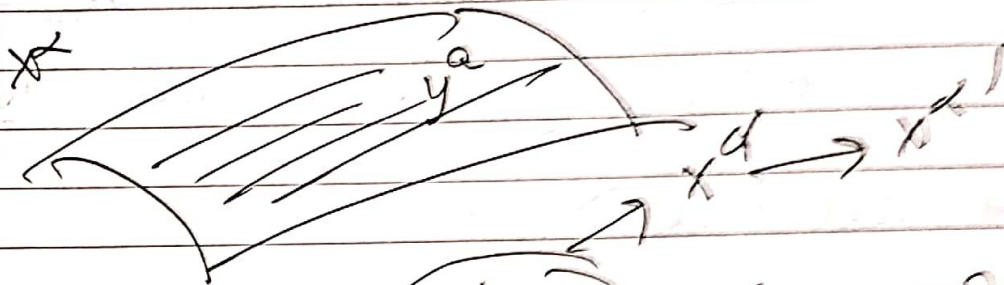
$$e_1^\alpha \equiv (0, 1, 0, 0)$$

$$e_2^\alpha \equiv (0, 0, 1, 0)$$

$$e_3^\alpha \equiv (0, 0, 0, 1)$$

$$K_{ab} \equiv \frac{\partial_t g_{ab}}{2} \Big|_{t=0}$$

(81) Two sets of coordinate freedom



What are the examples?

We can have  $x^a$  Arb,  $y^a$  fixed  
 $x^a$  fixed,  $y^a$  Arb  $y^a \rightarrow y'^a$

$x^a$  &  $y^a$  fixed

32

Tensors w.r.t. spacetime coord are scalar w.r.t.  $y^a \rightarrow y'^a$

eg.  $K_{ab}$

Tensors w.r.t.  $y^a \rightarrow y'^a$  are scalars  
 w.r.t.  $x^\alpha \rightarrow x'^\alpha$   
 $K_{ab} = \frac{\partial x^\alpha}{\partial y^a} \frac{\partial x^\beta}{\partial y^b} e_{\alpha\beta}$

33

Def  $K_{ab} \equiv \frac{\partial x^\alpha}{\partial y^a} \frac{\partial x^\beta}{\partial y^b} e_{\alpha\beta}$  Projection operator

Scalar under  $x^\alpha \rightarrow x'^\alpha$   
 Evaluate at QNC & see if matches

Projection on 3D

(34)  $\nabla_\beta n_\alpha = \partial_\beta n_\alpha - \Gamma_{\alpha\beta}^\gamma n_\gamma$

in GNC

$$\phi = t = \text{const.}$$

$$n_\alpha = \partial_\alpha \phi = (1, 0, 0, 0)$$

$$\therefore \nabla_\beta n_\alpha = 0$$

$$\nabla_\beta n_\alpha \stackrel{*}{=} -\Gamma_{\alpha\beta}^0$$

$$\nabla_{(\beta} n_{\alpha)} = \nabla_\beta n_\alpha + \nabla_\alpha n_\beta$$

$$\nabla_{(\beta} n_{\alpha)} \stackrel{*}{=} -\Gamma_{\alpha\beta}^0$$

$$\nabla_{(\beta} n_{\alpha)} e_a^\alpha e_b^\beta \stackrel{*}{=} -\Gamma_{\alpha\beta}^0 \delta_{ab} = -\Gamma_{ab}^0 \stackrel{*}{=} k_{ab}$$

how this is scalar

Scalar in spacetime

Equality of scalar in GNC

$\Rightarrow$  Equality in all coord

Cov.

$\therefore$  Def. of  $k_{ab}$  is valid

(35)

Can we go from specific GNC  $\rightarrow$  Covariant

Def. of  $k_{ab}$

36 Now Converting Riemann Tensor  $R_{abcd}$  & Contracted Einstein Tensor  $G_{ab}$  to Covariant form (Gauss today)

① & ⑥ cannot be written in covariant form. as they contain 2nd time derivative of metric & we don't have any geometrical structure analogous to  $\partial_t^2 g_{ab}|_{t=0}$

$\Rightarrow K_{ab} \equiv \nabla_{(b} n_{a)}$   $e^a_a e^b_b$

→ Gradient of normal vector along H.S.  
 → Tells us how normal vector varies along H.S.

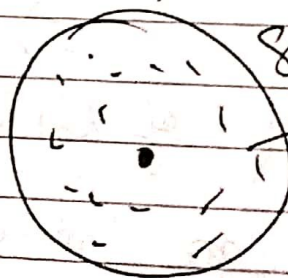
But to tell how normal vector varies away from surface, we don't know

as Normal is Only defined on H.S. Not away from H.S.

∴ Derivatives  $\nabla_b$  along those direction away from ~~normal~~ H.S. Not Defined.



Only on H.S.



Sphere → all directions

$$2 \times 2 \text{ Tab } t=0$$

to tell anything about this I have to know what is happening in the neighborhood of HoS  
 But from the given geometrical structure I don't have suff information.

### (37) Remaining Covariant Expression

$${}^4 R_{\mu\alpha\beta\gamma} n^\mu e_a^\alpha e_b^\beta e_c^\gamma \text{ is equivalent to } {}^4 R_{\text{tabc}} \text{ in } G_{\text{ref}}$$

as  $\{K_{abk} - K_{actb}\}$  is spacetime scalar  
 $\therefore$  LHS  ${}^4 R_{\text{tabc}}$  is scalar valid in any frame

$$\therefore {}^4 R_{\mu\alpha\beta\gamma} n^\mu e_a^\alpha e_b^\beta e_c^\gamma = K_{abk} - K_{actb}$$

Similarly

$${}^4 R_{\alpha\beta\gamma\delta} e_a^\alpha e_b^\beta e_c^\gamma e_d^\delta = R_{abcd} + K_{ac} K_{bd} - K_{ad} K_{bc}$$

Similarly

$$\text{Contracted } {}^4 G_{\mu\nu} n^\mu n^\nu = \frac{1}{2} (R - K^{ab} K_{ab} + K^2)$$

$${}^4 G_{\mu\alpha} n^\mu e_a^\alpha = D_b K_a^b - D_a K$$

→ Gauss Codazzi

How is it commutative?

# Initial Value Problem

L-12

① Mechanics  $m \ddot{x} = F$

∴ 2 Initial values to get Unique sol<sup>n</sup> ← 2<sup>nd</sup> order DE

Unique sol<sup>n</sup> Only if Initial value is provided  
eg.  $x(0)$  ;  $\dot{x}(0)$

Only by Eq<sup>n</sup> we can get many sol<sup>n</sup> But we get Unique sol<sup>n</sup> if Initial values are given

② field theory

Wave Eq<sup>n</sup>

$$-\frac{\partial^2 \phi}{\partial t^2} + \nabla^2 \phi = f \rightarrow \text{source}$$

$$\Rightarrow \nabla^2 \phi - f = \frac{\partial^2 \phi}{\partial t^2}$$

In mechanics we have finite DoF but in field theory we have ∞ DoF as  $\phi$  has value at every spatial position.

For Unique sol<sup>n</sup> to field Eq<sup>n</sup>

Initial Value:  $\phi(t=0, \vec{x})$ ,  $\partial_t \phi(t=0, \vec{x})$

③ By theorems of Uniqueness & Existence of PDE, we have well posed problem of  $\nabla^2 \phi - \frac{\partial^2 \phi}{\partial t^2} = f$  & 2 Initial values



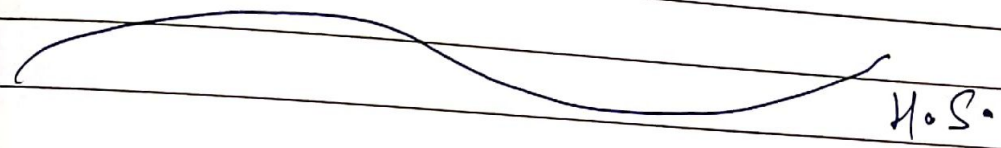
Q We are trying all this in GR to get the equivalent of

One Problem in field theory  $\square_{\eta^{\mu\nu}}$  was not covariant.  $\square_{\eta^{\mu\nu}}$  was that

in GR  $\square_{g^{\alpha\beta}} \nabla_{\alpha} \nabla_{\beta} \phi = \rho \Leftrightarrow \nabla^2 \phi - \frac{\partial^2 \phi}{\partial t^2} = \rho$

And for initial value

we have to take arbitrary data like spacelike H.S. & initial data has to be provided there. so that  $\square_{\eta^{\mu\nu}}$  becomes well posed.



$\phi$ : scalar field

$\Phi$ : H.S.

Initial values:  $\Phi(y^a) = \phi|_{\Sigma} \Leftrightarrow$  covariant version of  $\phi(t=0, \vec{x})$

Normal component of Derivative of scalar  $\Leftrightarrow n^{\alpha} \partial_{\alpha} \Phi(y^a)$

Uniqueness & Existence Theorem tells that  $\square_{\eta^{\mu\nu}}$  along with these initial values provide well posed problem.

L-13

1. for finite degree of freedom can be  
Generalized coordinate  $q(t)$  :
- ① Linear position variable
  - ② Angular position variable
  - ⋮
  - ⋮

Generalized velocity  $\dot{q}(t)$

Lagrangian function :  $L(q, \dot{q})$

Action functional  $S[q] = \int_{t_1}^{t_2} L(q, \dot{q}) dt$

② Def: Functional :  $f \xrightarrow{F} \mathbb{R}$

Here  $q \xrightarrow{S} \mathbb{R}$

$\uparrow$   
function

$\uparrow$   
Number

③ EOM : Hamilton's principle  $\delta S = 0$   
Action would be stationary in the neighborhood of the true path.

True path would be extremum of Action.

Initial condition  $\delta q(t_1) = \delta q(t_2) = 0$

If this is not then  $\uparrow$  we won't have well defined variational principle

# ④ Euler Lagrange Equation

$$\frac{\partial L}{\partial q} = \frac{d}{dt} \frac{\partial L}{\partial \dot{q}}$$

# ⑤ Scalar field theory in Curved spacetime

$$\begin{cases} \phi(x^i) \\ \partial_\alpha \phi(x^i) \end{cases} \rightarrow \infty \text{ no. of dof.}$$

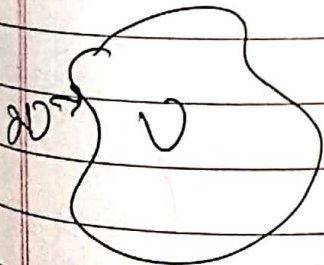
Lagrangian Density = Lagrangian per Unit Vol.

$$\mathcal{L}(\phi, \partial_\alpha \phi) = \text{scalar fn.}$$

# ⑥ Action functional $S[\phi] = \int_V d^4x \mathcal{L} \sqrt{-g}$

$V =$  fixed finite 4D region

$\partial V :$  Boundary closed 3 surface



Why not vary this?

# ⑦ $\delta\phi = 0$ on $\partial V$

$$\delta S = \int_V \left( \frac{\partial \mathcal{L}}{\partial \phi} \delta\phi + \frac{\partial \mathcal{L}}{\partial \phi_{,\alpha}} \partial_\alpha \delta\phi \right) \sqrt{-g} d^4x$$

keeping the boundary fixed

$$= \int \frac{\partial \alpha}{\partial \phi} \delta \phi \sqrt{g} + \int \left( \frac{\partial \alpha}{\partial \phi} - \nabla_\alpha \frac{\partial \alpha}{\partial \phi, \alpha} \right) \delta \phi \sqrt{g} d^4x$$

$$\therefore \frac{\partial \alpha}{\partial \phi} - \nabla_\alpha \frac{\partial \alpha}{\partial \phi, \alpha} = 0$$

⑧ Example:  $\alpha = + \frac{1}{2} g^{\alpha\beta} \partial_\alpha \phi \partial_\beta \phi - V(\phi)$

Why + sign?

Going to LIF.

$$\alpha = \frac{\eta^{\alpha\beta} \partial_\alpha \phi \partial_\beta \phi - V(\phi)}{2}$$

$$\eta^{00} = 1$$

$$\therefore \alpha = \frac{\partial_t \phi}{2} - V(\phi) - - - -$$

$\partial_t \phi$  has to come with the sign + sign there.

if our convention  $\eta_{\alpha\beta}$   
 $\eta^{00} = -1$   $\therefore$  There has to be -ve sign

$$\nabla_\alpha \left( \frac{\partial L}{\partial \phi_{,\alpha}} \right) = + g^{\alpha\beta} \nabla_\alpha \nabla_\beta \phi \equiv - \square \phi$$

$$\square \equiv \nabla_\alpha \nabla^\alpha$$

AS  $\phi$  is fnd of  $\phi, \alpha$

$$\therefore \frac{\partial \mathcal{L}}{\partial \phi} = - \frac{dV}{d\phi}$$

field eqn  $\square \phi = \frac{dV}{d\phi}$

free massless field  $V = 0$

we would get linear eqn

free massive field  $V = \frac{m^2}{2} \phi^2$

As it is linear we call it free

this would yield Klein Gordon eqn in curved space

Interacting field  $V = \frac{m^2}{2} \phi^2 + \lambda \phi^4$

gives non linear eqn  $\therefore$  Interacting

Self Interacting

(10) for Vector field

$$S = S_g [g] + S_m [\phi, g]$$

$\partial V$  is almost nowhere null.



$$S_g = \frac{1}{16\pi} \int_V R \sqrt{-g} d^4x + \frac{1}{8\pi} \int_{\partial V} \epsilon_{\alpha\beta\gamma\delta} \sqrt{-g} d^3y$$

$$S_m [\phi, g] = \int_V \alpha(\phi, \partial_\alpha \phi) \sqrt{-g} d^4x$$

In field theory  
there was dependence of  $\phi, \partial_\alpha \phi$  not higher  
order

here it should be dependent on  $g, \partial_\alpha g$ .  
But  $\Gamma = (g, \partial_\alpha g)$

is not scalar But  $\alpha$  has to be scalar  
 $\therefore$  to construct a scalar  $\alpha$  put  $R$  in  $S$ .

# Functional Derivative

① Functional derivative or variational derivative relates a change in functional to a change in a function on which functional depends.

② Let the functional :

$$J[f] = \int_a^b L(x, f(x), f'(x)) dx$$

If the  $f$  is varied adding to it a function  $\delta f$  and the resulting integrand  $L(x, f + \delta f, f' + \delta f')$  is expanded in powers of  $\delta f$ , then the coefficient of  $\delta f$  in first order term is called functional derivative  $\delta J$ .

$$\delta J = \int_a^b \left( \frac{\partial L}{\partial f} \delta f + \frac{\partial L}{\partial f'} \frac{d(\delta f)}{dx} \right) dx$$

$\downarrow$   
 $f(x+\epsilon) - f(x)$   
 $f'(x)\epsilon + \frac{\epsilon^2}{2} f''(x)$

Definition:

③ Functional derivative of  $F[p] \equiv \frac{\delta F}{\delta p}$  is defined as:

$$\int \frac{\delta F}{\delta p} \phi(x) dx = \lim_{\epsilon \rightarrow 0} \frac{F[p + \epsilon \phi] - F[p]}{\epsilon}$$

$$= \left. \frac{d}{d\epsilon} F[p + \epsilon \phi] \right|_{\epsilon=0}$$

where  $\phi$  is arbitrary function &  $\epsilon \phi$  is variation of  $p$

④ The differential of the functional  $F[p]$  is (b)

$$\delta F[p; \phi] = \int \frac{\delta F}{\delta p} \phi dx$$

Let  $\phi = \delta p \therefore \phi$  be change  $p$

⑤ Similarity to Total Differentiation ②  $f(x)$

Let  $F$  be function  $F(p_1, p_2, \dots, p_n)$

$$dF = \sum \frac{\partial F}{\partial p_i} dp_i$$

where  $p_1, p_2, \dots, p_n$  are independent variables. Deriv w.r.t

But  $\delta F[\phi] = \int \left( \frac{\delta F}{\delta p} \right) (\delta p) dx$

$$\frac{\delta F}{\delta p} \equiv \frac{\partial F}{\partial p_i}$$

Eg.

⑥ Let the functional be  $F[p] = \int f(x, p(x), \nabla p(x)) dx$

$$\delta F[p; \phi_1, \phi_2] = \int \frac{\delta F}{\delta p} \phi(x) dx = \left[ \frac{d}{d\epsilon} F \right]_{\epsilon=0}$$

$$= \left[ \frac{d}{d\epsilon} \int f(x, p + \epsilon \phi, \nabla p + \epsilon \nabla \phi) dx \right]_{\epsilon=0}$$

$$= \int \lim_{\epsilon \rightarrow 0} \frac{f(x, p + \epsilon \phi, \nabla p + \epsilon \nabla \phi) - f(x, p, \nabla p)}{\epsilon} dx$$

$$= \int \lim_{\epsilon \rightarrow 0} \frac{f(x, p, \nabla p) + \frac{\partial f}{\partial p} \epsilon \phi + \frac{\partial f}{\partial (\nabla p)} \epsilon \nabla \phi - f}{\epsilon} dx \quad \text{⑦ } F$$

Taylor Exp<sup>n</sup>

①  $f(x)$  around  $x_0$

$$f(x) = f(x_0) + f'(x_0) (x - x_0) + \frac{f''(x_0)}{2!} (x - x_0)^2 + \dots$$



Around  $x_0$   
↑

$$(2) f(x_0 + \epsilon) = f(x_0) + f'(x_0) \epsilon + f''(x_0) \frac{\epsilon^2}{2!} -$$

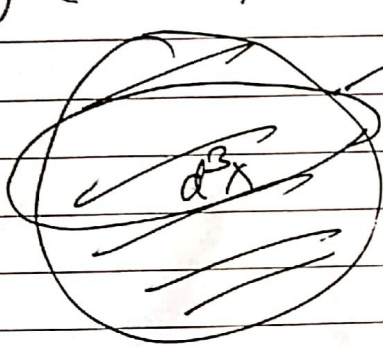
$$\vec{\nabla} \phi = \int \left( \frac{\partial f}{\partial p} \phi + \frac{\partial f}{\partial(\nabla p)} \nabla \phi \right) d\vec{r}$$

Derivative of Scalar  
w.r.t. vector

let  $\frac{\partial f}{\partial(\vec{\nabla} p)} = A$

$$= \int \left[ \frac{\partial f}{\partial p} \phi + \vec{\nabla} \cdot \left( \frac{\partial f}{\partial(\nabla p)} \phi \right) - \left( \nabla \cdot \frac{\partial f}{\partial(\nabla p)} \right) \phi \right] d\vec{r}$$

$$\int \left( \nabla \cdot \frac{\partial f}{\partial(\nabla p)} \phi \right) d\vec{r} = \int (\nabla \cdot \vec{A}) \phi d\vec{r} = \int \vec{A} \cdot \vec{n} \phi d\vec{x}$$



let on surface  $\phi = 0$

i.e.  $\delta p$  on surface = 0

$$\therefore = \int \left( \frac{\partial f}{\partial p} \phi + \vec{\nabla} \cdot \frac{\partial f}{\partial(\nabla p)} \phi \right) d^3x$$

$$\frac{\delta F}{\delta p} = \frac{\partial f}{\partial p} - \nabla \cdot \frac{\partial f}{\partial(\nabla p)}$$

### (7) Fundamental Lemma of Calc. of Variation

$$\int_a^b f(x) h(x) dx = 0$$

if  $f$  is cont. f<sup>n</sup> in  $(a, b)$

for smooth  $h(x)$  in  $(a, b)$  then  $f(x) = 0$

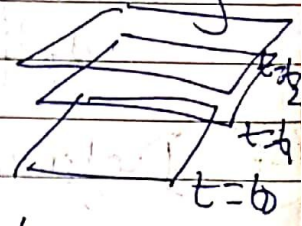
①  $\dot{q} = \frac{\partial L}{\partial p} = f(q, \dot{q})$  Assuming  $\dot{q} = g(q, p)$   
 $H = p\dot{q} - L = H(p, q)$   
 can be extracted

② Vary the Lagrangian  $L = p\dot{q} - H(p, q)$   
 $\int_{t_1}^{t_2} \delta(p\dot{q} - H) dt$

$\delta q(t_1, t_2) = 0 \Rightarrow \left. \begin{aligned} \dot{p} &= -\frac{\partial H}{\partial q} \\ \dot{q} &= \frac{\partial H}{\partial p} \end{aligned} \right\} \text{Hamilton's Equations}$

③ But here we are interested in getting Hamiltonian & not Hamilton's Eqn  
 $\therefore$  Construct Hamiltonian for field theory of GR.

④ Field theory in flat spacetime



$\mathcal{L}(\phi, \partial_\alpha \phi) \leftrightarrow \pi^\alpha = \frac{\partial \mathcal{L}}{\partial(\partial_\alpha \phi)}$

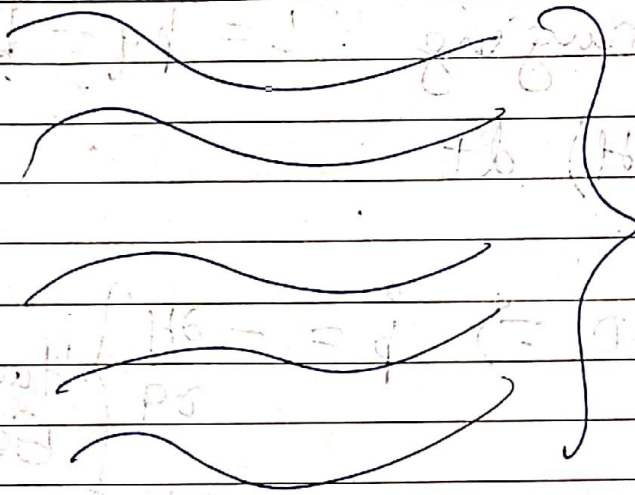
At level of Hamiltonian  $\rightarrow$  Lorentz Invariance Over  $\therefore$  Lorentz invariance is gone away. selected the frame

⑤  $H = \pi^\alpha \partial_\alpha \phi - \mathcal{L} = T_{00}$   
 $H = \int H d^3x = \text{Total Energy of field}$

To express action in terms of the Hamiltonian it is necessary to foliate  $V$  with a family of spacelike H.S.

⑤ field theory in Curved Spacetime

Foliate spacetime with arbitrary spacelike Hyper Surfaces.



Any shape  
Only condition:  
It doesn't Intersect & they are spacelike.

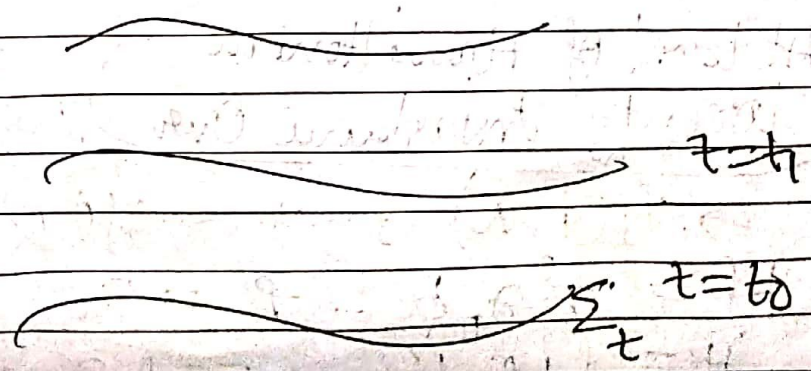
⑥ Analog of time derivative (how field are changing) ~~along the H.S.~~ is the normal derivative of field.

$$\partial_0 \phi \longrightarrow n^\alpha \partial_\alpha \phi$$

⑦ Define time function  $\rightarrow$  scalar field.

$t(x^\alpha)$ , s.t.  $t = \text{const}$  on each  $\Sigma_t$

$x^0 \neq t$



$t$  is a good candidate to call time because it keeps on increasing on the spacelike surfaces

PAGE NO.:

DATE: / /20

(8) I have the freedom to use  $t = x^0$  in  $(t, x^1, x^2, x^3)$  as new coordinates instead of  $(x^0, x^1, x^2, x^3)$  due to general covariance.

But in general  $t = x^0$  still  $t$  is a good function to be called time as  $\uparrow$  in surface

(9) In our coord. system

$$t(x^\alpha) = \text{const. on each } \Sigma$$

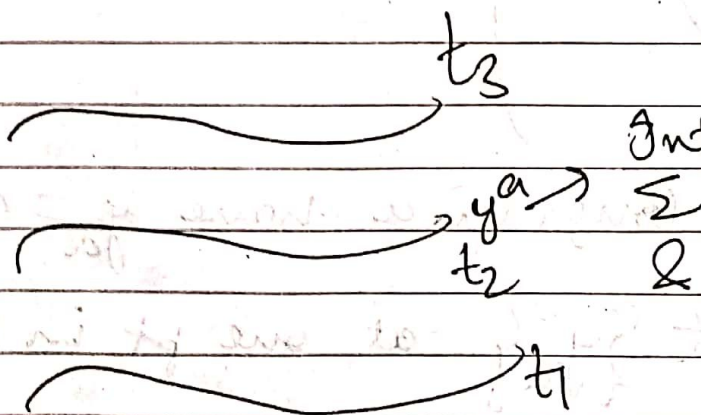
$\therefore t$  is just a scalar

(10)  $n_\alpha \propto \partial_\alpha t$

$\uparrow$   
has to be Normalized

$$n_\alpha n^\alpha = 1$$

(11)



Intrinsic coord. on  $\Sigma$

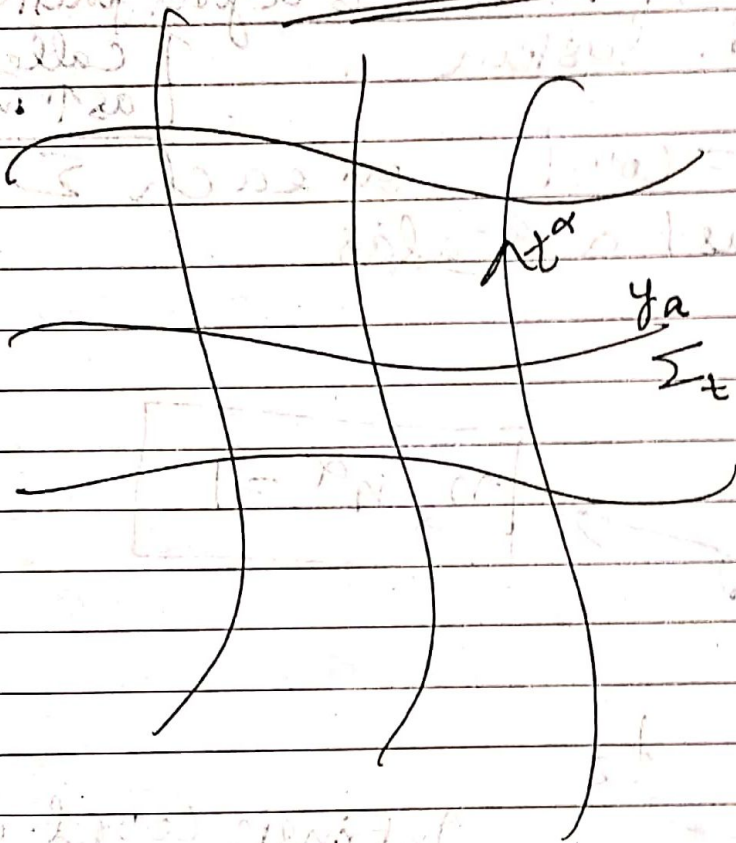
& coord. could be diff. on diff. H.S.

like on  $t = t_1$  we use Cartesian  $(x, y, z)$

& on  $t = t_2$  we use sph.  $(r, \theta, \phi)$   
But all this will cause difficulty for no reason

(12) For this finding relations, construct congruence (non intersect)

no geodesic  
NO H.S.O



~~Let~~ let these congruence have  $y_a = \text{constant}$

& if I select  $\{y_a\}$  at one pt in H.S

of one H.S. It will carry to all H.S. at that pt. on H.S. carried by curve

Now do this for every curve  $\{y_a^1, y_a^2, y_a^3, \dots\}$

(14) Take  $t(x^\alpha)$  as parametrization of curve

Tangent vector field =  $t^\alpha$

$\therefore$  Disp. along curve  $dx^\alpha = t^\alpha dt$

$$x^\alpha \equiv X(y^\alpha, t)$$

$$x^\alpha(y^\alpha, t) \therefore dx^\alpha = \left( \frac{\partial x^\alpha}{\partial y^a} \right)_t dy^a + \left( \frac{\partial x^\alpha}{\partial t} \right) dt$$

(15) Another way to look at it.

⇒ Change in  $t$  ( $x^\alpha$ )

$$dt = \frac{\partial t}{\partial x^\alpha} dx^\alpha \quad (\text{Tone for any Displacement})$$

Along the curve  $dx^\alpha = t^\alpha dt$

$$dt = \left( \frac{\partial t}{\partial x^\alpha} t^\alpha \right) dt$$

$$\therefore \frac{\partial t}{\partial x^\alpha} t^\alpha = 1$$

$t^\alpha$ : tangent vector  
 $\frac{\partial t}{\partial x^\alpha}$ : Gradient of  $t$  wrt  $x^\alpha$

(16) Original coord sys  $\{x^\alpha\}$

By construction coord. sys  $\{y^a, t\}$

$y^a$ : Selects the curve

$t$ : Selects the pt. where I am at curve

And in general  $x^\alpha = f(t, y^a)$ : Parameteric Eqn

(17)

$$\left( \frac{\partial x^\alpha}{\partial t} \right)_{y^a} = t^\alpha$$

→ moving along one of the Curve

$$\left( \frac{\partial x^\alpha}{\partial y^a} \right)_t = e_a^\alpha = \text{Displacements along H.S.} = \text{Tangent vectors along H.S.}$$

(12) (18)  $\partial_t e^a = 0$

(19) Normal vector

check (10)

It is not compulsory that  $n^\alpha \parallel t^\alpha$

i.e. Those curves don't have to be H.S.O.

$$n_\alpha = t N \partial_\alpha t$$

↓  
lapse fn

↓

How? It is the measure of proper distance  
B/w one H.S & other

(20)  $n_\alpha e^a = 0$

(21) Decompose  $t^\alpha$  into  $\{n_\alpha, e^a\}$

$$t^\alpha = N n^\alpha + N^a e^a$$

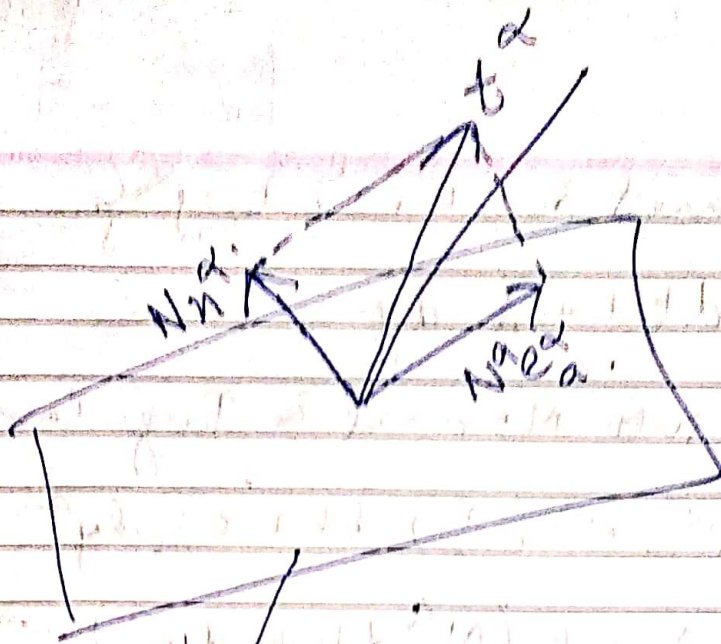
↓

lapse fn

↓

shift vector

(22)



(23)

Proof.  $t^\alpha = N n^\alpha + N^\alpha e_a^\alpha$

let

$$t^\alpha = A n^\alpha + N^\alpha e_a^\alpha \quad \text{By Def.}$$

$t^\alpha \partial_\alpha t = 1 \Rightarrow$  By Def. of lapse for

$$t^\alpha \left( -\frac{n^\alpha}{N} \right) = \left( A n^\alpha + N^\alpha e_a^\alpha \right) \left( +\frac{n^\alpha}{N} \right)$$

$$1 = \frac{A}{N}$$

$$\therefore \underline{\underline{A = N}}$$

(24)

$\therefore$  we can define lapse either

$$\begin{aligned} n^\alpha &= N \partial_\alpha t \\ \text{or} \\ t^\alpha &= N n^\alpha + N^\alpha e_a^\alpha \end{aligned}$$



(25) What is the metric in  $\{t, y^a\}$

$$dx^\alpha = t^\alpha dt + e_a^\alpha dy^a$$

Break this into Normal & Tang. Comp.

$$= (N n^\alpha + N^a e_a^\alpha) dt + e_a^\alpha dy^a$$

$$= (N dt)^\alpha + (N^a dt + dy^a) e_a^\alpha$$

$$ds^2 = g_{\alpha\beta} dx^\alpha dx^\beta$$

$$ds^2 = N^2 dt^2 + h_{ab} (dy^a + N^a dt)(dy^b + N^b dt)$$

3+1 Decomposition

(26) For Displacement along curve  $dy^a = 0$

$$ds^2 = N^2 dt^2 + h_{ab} N^a N^b dt^2$$

Increment in proper time Related to coordinate time  $t$

$$dt^2 = (N^2 + h_{ab} N^a N^b) dt^2$$

check 19.

(27) for H.S.O.  $N^a = 0$

$$\text{as } t^\alpha = N n^\alpha + N^a e_a^\alpha$$

∴  $dc^2 = N^2 dt^2$  for HSO  
check 19

28) Disp. along H.S.  
 $ds^2 = h_{ab} dy^a dy^b$

This is what we call the Def'n.

29)  $\sqrt{-g} = N \sqrt{h}$

30) Hamiltonian of field theory  
 $\mathcal{L}(\phi, \nabla_a \phi)$

Earlier  
 $\partial_0 \phi \longrightarrow n^\alpha \partial_\alpha \phi$   
time Derivative associated with Normal

But this is not general.

assume ~~to~~ parameters along flow  
tangent along congruence  
n<sub>a</sub> ~~X~~ t<sub>a</sub>

Not general (GO along flow is more general than going along Normal)

(25) (31)  $\partial_t \phi \xrightarrow{\text{generalize to}} \alpha_{\mu\nu} \phi = \dot{\phi}$   
 for  $\phi$  : scalar

$$\alpha_{\mu\nu} \phi = \eta^{\mu\nu} \partial_\nu \phi = \frac{d\phi}{dt}$$

for scalar field would go out but to reality of  $\phi$ !

(32) Canonical Momentum

Definition  

$$\pi \equiv \frac{\partial(\sqrt{-g} \mathcal{L})}{\partial \dot{\phi}}$$

$\mathcal{L}(\phi, \partial_\alpha \phi)$   
 scalar  
 $\frac{d\phi}{dt} = \text{scalar}$

Not a scalar (due to  $\sqrt{-g}$ ) why?  
 But a scalar density.

(33) Hamiltonian Density  
 $\mathcal{H}(\phi, e^\alpha_\mu \partial_\alpha \phi, \pi)$

$$\mathcal{H}(\phi, e^\alpha_\mu \partial_\alpha \phi, \pi)$$

$$\mathcal{H} = \pi \dot{\phi} - \sqrt{-g} \mathcal{L} \quad \text{scalar density.}$$

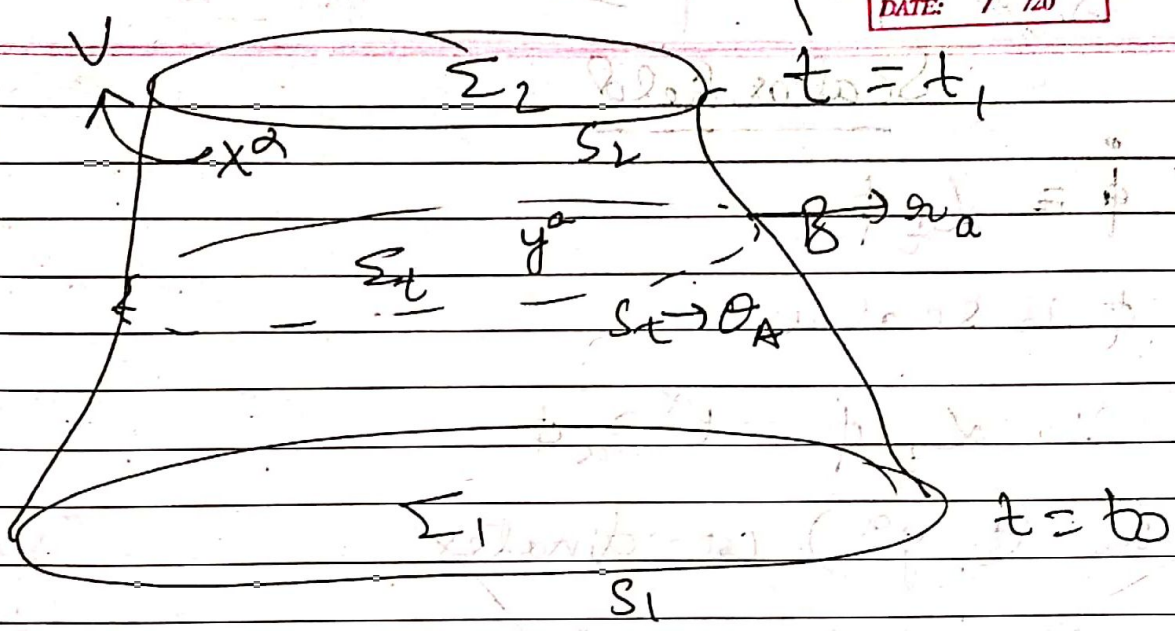
Not a scalar / scalar

$$H = \int \mathcal{H} d^3x$$

No  $\mathcal{H}$  because already there

(34) GR formulation

$$S_G = \int_V R F_g d^4x + 2 \int_{\partial V} \epsilon_{\mu\nu\alpha\beta} \Gamma^{\mu\nu\alpha}{}_\gamma dy^3$$



$$\partial V = \Sigma_1 + \Sigma_2 + B(\partial A) \quad V(x^\alpha)$$

$V$  is foliated by  $\Sigma_t(y^a)$

All H.S. also have boundaries  $S_t$

$\Sigma_t$  is bounded by  $S_t(\partial A)$

for  $\Sigma$  is foliated by  $S_t$   
for  $\Sigma$   
 $\phi(x^\alpha) = \text{const.}$

for  $S_t$   
 $\phi(y^a) = \text{const}$

$x^\alpha(y^a)$   $f^n$  3 par.

$y^a(\partial A)$   $f^n$  2 par

$n_\alpha = \text{Normal to } \Sigma$

$n_a = \text{Normal to } S_t$

$$e_b^\alpha = h^a e_a^\alpha$$

Associated vector

# Covariant derivative of spacetime

PAGE NO.:

DATE: / / 20

## Scalar field

$$\textcircled{1} \quad \dot{\phi} \equiv d_t \phi$$

$\phi$  is scalar

$$\therefore d_t \phi = t^\alpha \partial_\alpha \phi$$

~~② in  $(t, y^a)$  coordinates~~

~~$$t^\alpha = \left( \frac{dx^\alpha}{dt} \right) \Rightarrow t^0 = 1;$$~~

~~$$t^i = \frac{dy^i}{dt}$$~~

~~$$\left( \frac{dx^\alpha}{dt} \right) = \left( \frac{\partial x^\alpha}{\partial t} \right)_{y^a} + \left( \frac{\partial x^\alpha}{\partial y^a} \right) \frac{dy^a}{dt}$$~~

~~$$t^\alpha \partial_\alpha t = 1$$~~

~~$$\left( \frac{dy^a}{dt} \right) \left( \frac{\partial \phi}{\partial y^a} \right)_{t^a}$$~~

~~③  $\frac{\partial \phi}{\partial t}$~~

$$d_t \phi = t^\alpha \partial_\alpha \phi$$

$$\frac{dx^\alpha}{dt} = \left( \frac{\partial x^\alpha}{\partial t} \right)_{y^a} + \left( \frac{\partial x^\alpha}{\partial y^a} \right) \frac{dy^a}{dt}$$

Along the curve

$$\left( \frac{\partial x^\alpha}{\partial t} \right)_{y^a} = \frac{dx^\alpha}{dt}$$

in  $(t, y^a)$ .

$$t^\alpha = \frac{dx^\alpha}{dt} = (1, 0, 0, 0)$$

$$d_t \phi = \frac{\partial \phi}{\partial t}$$

$$\left( \frac{dy^a}{dt} \right) \left( \frac{\partial \phi}{\partial y^a} \right) = 0$$

$$\therefore \frac{dx^\alpha}{dt} = \left( \frac{\partial x^\alpha}{\partial t} \right)_{y^a}$$

$$e_a^\alpha = \frac{\partial x^\alpha}{\partial y^a}$$

④  $\frac{\partial \phi}{\partial y^a} \equiv \frac{\partial \phi}{\partial x^a} e_a^\alpha$  spatial Derivative

⑤  $\mathcal{L}(q, \dot{q}, t) \longrightarrow \mathcal{L}(\phi, \mathcal{L}_t \phi, \partial_a \phi e_a^\alpha)$   
Density

$$p = \frac{\partial \mathcal{L}}{\partial \dot{q}}$$

$$\pi = \frac{\partial \mathcal{L}(\sqrt{g})}{\partial (\mathcal{L}_t \phi)}$$

$$q(\phi, \dot{q})$$

$$\phi(\phi, \mathcal{L}_t \phi, \pi)$$

$$H = p \dot{q} - \mathcal{L}$$

$$\mathcal{H} = \pi \mathcal{L}_t \phi - \mathcal{L}(\sqrt{g})$$

$$H(p, q)$$

$$\mathcal{H}(\phi, \mathcal{L}_t \phi, \pi)$$

- 25 (3) (b) Lagrangian is scalar.  
Hamiltonian is also scalar.

Here

Hamiltonian is not a scalar.

32 (P)  $H = \int h$   $H_{\text{scal}} = \frac{\int q}{N} H_{\text{scal}}$

$$H(p, q) = \int H d^3y$$

functional  $\Sigma_t$

33 (Q)  $A = \int \mathcal{L} d^4x$   
 $= \int (\pi \dot{\phi} - H) d^4x$

33  $= \int_{t_1}^{t_2} dt \int_{\Sigma_t} (\pi \dot{\phi} - H) d^3y$

34 (9)  $\int_{t_1}^{t_2} dt \frac{d}{dt} \int_{\Sigma_t} (\pi \dot{\phi} - H) d^3y$

34  $\int_{t_1}^{t_2} d \int_{\Sigma_t} (\pi \dot{\phi} - H) d^3y$

$$\int_{x_1}^{x_2} dx$$

$$x_2 - x_1$$

$$\int_{\Sigma_2} (\pi \dot{\phi} - H) d^3y - \int_{\Sigma_1} (\pi \dot{\phi} - H) d^3y$$

(16)  $\int_V (\partial_\alpha A^\alpha) d^4x = \int_{\partial V} A^\alpha d\Sigma_\alpha$   $d\Sigma_\alpha = dx^1 dx^2 dx^3 n_\alpha$

PAGE NO.:  
DATE: / / 20

(25)  $\int_V (\nabla_\alpha A^\alpha) F g d^4x = \int_{\partial V} A^\alpha d\Sigma_\alpha$

$d\Sigma_\alpha = \sqrt{h} d^3y \cdot n_\alpha$

(31)  $\int_V \partial_\alpha A^\alpha d^3y = \int_{\partial V} A^\alpha dS_\alpha$   $dS_\alpha = r_a^2 dy^1 dy^2 dy^3$

(32)  $\int_V \nabla_\alpha A^\alpha \sqrt{h} d^3y = \int_{\partial V} A^\alpha dS_\alpha$   $dS_\alpha = r_a^2 \sqrt{h} dy^1 dy^2 dy^3$

$\frac{\partial H_\alpha}{\partial(\partial_\alpha q)} \delta(\partial_\alpha q) \sqrt{h} d^3y$

$\int \partial_a \left( \frac{\partial H_\alpha}{\partial(\partial_a q)} \delta q \right) \sqrt{h} dy^1 dy^2 dy^3 - \int \partial_a \left( \frac{\partial H_\alpha}{\partial(\partial_a q)} \right) \delta q \sqrt{h} dy^1 dy^2 dy^3$

(33)  $\partial_\alpha \phi \equiv \frac{\partial \phi}{\partial x^\alpha} e^\alpha_a$

$\nabla_a \phi \equiv e^\alpha_a \partial_\alpha \phi$

$\nabla_a A^\beta = \partial_\alpha A^\beta e^\alpha_a + A^\beta e^\alpha_a \omega^\beta_\alpha$

(34)  $\nabla_a \phi = \nabla_\alpha \phi e^\alpha_a = \partial_\alpha \phi e^\alpha_a$

$\int \nabla_a \left( \frac{\partial H_\alpha}{\partial(\partial_a q)} \delta q \right) \sqrt{h} dy^1 dy^2 dy^3 - \int \nabla_a \left( \frac{\partial H_\alpha}{\partial(\partial_a q)} \right) \delta q \sqrt{h} dy^1 dy^2 dy^3$



$$x_{\bar{\mu}} = \eta_{\bar{\mu}\alpha} \Lambda_{\bar{\beta}}^{\alpha} \eta^{\bar{\beta}\gamma} x_{\gamma}$$

PAGE NO.:

DATE: / / 20

$$\frac{\partial x_{\gamma}}{\partial x_{\bar{\mu}}} = (\eta \Lambda \eta)^{\top}$$

$$(\Lambda^{\top})^{\alpha}_{\beta} = \Lambda_{\beta}^{\alpha}$$

$$= \Lambda_{\beta\gamma} \Lambda^{\gamma\alpha}$$

$$= \Lambda$$

$$\Lambda_{\beta}^{\alpha} = \Lambda_{\beta\gamma} \Lambda^{\gamma\alpha}$$

$$\Lambda_{\beta\alpha} = \Lambda_{\beta}^{\gamma} \Lambda^{\gamma\alpha}$$

$$\Lambda_{\beta}^{\alpha} \Lambda^{\beta\gamma} = \Lambda^{\gamma\alpha}$$

$$\Lambda_{\beta\alpha} = \Lambda_{\beta\gamma} \Lambda^{\gamma\alpha}$$

$$\Lambda_{\beta}^{\alpha} = \Lambda_{\beta\gamma} \Lambda^{\gamma\alpha}$$

$$\Lambda_{\beta}^{\alpha} = \Lambda_{\beta\delta} \Lambda^{\delta\gamma} \Lambda^{\gamma\alpha}$$

$$\Lambda_{\beta}^{\alpha} = \Lambda_{\beta\delta} \Lambda^{\delta\gamma} \Lambda^{\gamma\alpha}$$

2  
x  
1  
x<sub>2</sub> - x

PAGE NO.:

DATE: / / 20

(3) 3+1 formulation matter action also if  $g$  have matter.

①  $\Sigma_t$ :

$$\left\{ \begin{aligned} t(x^\alpha) &= \text{const.} \\ x^\alpha &= x^\alpha(y^a) \quad \text{4 par } \rightarrow \text{3 par.} \\ h_{ab} &= g_{\alpha\beta} e_a^\alpha e_b^\beta \\ g_{\alpha\beta} &= e_n^\alpha e_n^\beta + h^{ab} e_a^\alpha e_b^\beta \\ n_\alpha &\propto \partial_\alpha t \\ e_a^\alpha &= \frac{\partial x^\alpha}{\partial y^a} \\ K_{ab} &= \nabla_a n_b^\alpha e_a^\alpha e_b^\beta \end{aligned} \right.$$

②  $S_t$

Embedded in 3D  $\Sigma_t$

$$\left\{ \begin{aligned} \phi(y^a) &= \text{const.} \\ y^a &= y^a(\theta^A) \quad \text{3 par } \rightarrow \text{2 par} \\ \sigma_{AB} &= h_{ab} e_A^a e_B^b \\ h_{ab} &= \epsilon_{ab} z^a z^b + \sigma_{AB} e_A^a e_B^b \\ z_a &\propto \partial_a \phi \\ e_A^a &= \frac{\partial y^a}{\partial \theta^A} \end{aligned} \right.$$

2 Dim. Ext. Curv.

$$K_{AB} = \nabla_a z_b^a e_A^a e_B^b$$

3) We can also embed it in 4D  
2D embedding 4D spacetime.

$S_t$  embed in spacetime.

(4)  $\varphi(x^\alpha) = \text{const.}$

$\Rightarrow x^\alpha = x^\alpha(\theta^A)$  4<sup>th</sup> 2 par.  
 $= x^\alpha(y^a) = x^\alpha(y^a(\theta^A))$

$\Rightarrow e_A^\alpha = \frac{\partial x^\alpha}{\partial \theta^A} = \frac{\partial x^\alpha}{\partial y^a} \frac{\partial y^a}{\partial \theta^A}$

$= e_a^\alpha e_A^a = \text{Projection } e_a^\alpha \text{ to } S_t$

$\Rightarrow r^\alpha = r^a e_a^\alpha$   
Push forward

3D. Tangent vector on  $\Sigma_t$

$\Rightarrow \sigma_{AB} = h_{ab} e_A^a e_B^b$

$= (g_{\alpha\beta} e_a^\alpha e_b^\beta) e_A^a e_B^b$

$= g_{\alpha\beta} e_A^\alpha e_B^\beta$

$\Rightarrow \nabla_a r_b = \nabla_\alpha r_\beta e_a^\alpha e_b^\beta$

$K_{AB} = \nabla_a r_b e_A^a e_B^b$

$\sigma_{AB} = \nabla_{AB} r = K_{AB}$

$= \nabla_\alpha r_\beta e_A^\alpha e_B^\beta$

2Dim. Extrinsic

Comp letureshms Rehu

$g^{\alpha\beta} = n^\alpha n^\beta + e^\alpha e^\beta + \sigma^{AB} e_A^\alpha e_B^\beta$

⑤ Bounded in spacetime

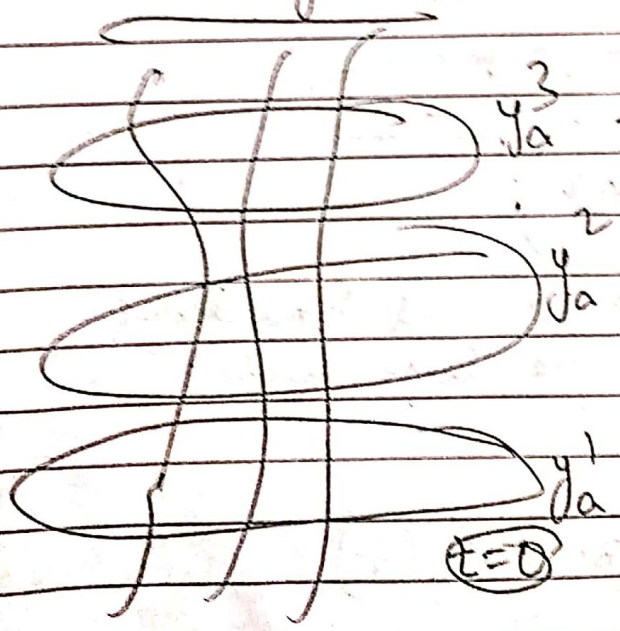
$\Rightarrow \xi^{\alpha} = (1, 0, 0, 0)$   
 $x^{\alpha} = x^{\alpha}(z^i) \quad i, j, k$

$\Rightarrow \xi^{\alpha} = \partial_{\alpha} \xi$   
 $e_j^{\alpha} = \frac{\partial x^{\alpha}}{\partial z^j}$

$\Rightarrow g_{ij} = g_{\alpha\beta} e_j^{\alpha} e_i^{\beta}$   
 $g_{ij} = \nabla_{\alpha} g_{\beta\gamma} e_j^{\alpha} e_i^{\beta}$  with  $g_{ij} = g_{ji}$

$\Rightarrow g^{\alpha\beta} = e^{\alpha}_i e^{\beta}_j$

⑥ Foliation of  $\mathcal{B}$  by  $S_t$



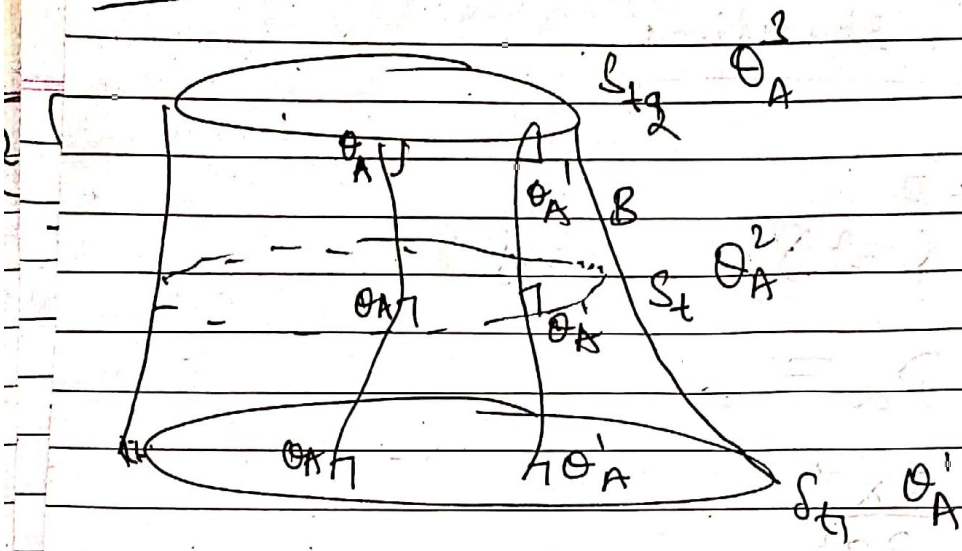
Relate  $y_a$  by setting conditions on congruences.

$t^{\alpha} = \frac{\partial x^{\alpha}}{\partial t}$  along Curve

$t^{\alpha} = \frac{dx^{\alpha}}{dt}$

$dt = \frac{\partial t}{\partial x^{\alpha}} dx^{\alpha} = \left( \frac{\partial t}{\partial x^{\alpha}} t^{\alpha} \right) dt$

Here



Relating  $\theta_A^1, \theta_A^2, \theta_A^3$   
by congruence on Boundary.

i.e. New long. of curves on B along which  $\theta_A$  is constant along the curve.

Restriction: Assume H.S.O.

congruence Orthog. to  $S_t$

$\therefore N \neq 0 \Rightarrow$  shift vector = 0

$(t, \theta_A) \implies (z^i)$

$B_t^\alpha \equiv \left( \frac{\partial x^\alpha}{\partial t} \right)_{\theta_A} =$  Tangent vector at Boundary along the congruence.

$B_t^\alpha = N n^\alpha$  (zero shift)

$n_\alpha = N \partial_\alpha t$

(9) ~~Referring to (6)~~

as

$$(t, y^a) \equiv (x^\alpha)$$

$$\text{Hence } (t, \theta_A) \equiv (z^i)$$

Disregarding  $x^\alpha$  &  $z^i$

working in  $(t, y^a)$  &  $(t, \theta_A)$  coord.

(10) Choosing  $z^i = (t, \theta_A)$

$$dx^\alpha = \left( \frac{\partial x^\alpha}{\partial t} \right)_{\theta_A} dt + \left( \frac{\partial x^\alpha}{\partial \theta_A} \right) d\theta_A$$

Displacement  
on B

$$= B_t^\alpha dt + e_A^\alpha d\theta_A$$

$$= N n^\alpha dt + e_A^\alpha d\theta_A$$

$$n_A e_A^\alpha = 0$$

~~Earlier Today~~

$dx^\alpha$

Displacement in Spacetime

$$dx^\alpha = \left( \frac{\partial x^\alpha}{\partial t} \right)_{y^a} dt + \left( \frac{\partial x^\alpha}{\partial y^a} \right) dy^a$$

$$= t^\alpha dt + e_a^\alpha dy^a$$

$$= (N dt) n^\alpha + (N^a dt + dy^a) e_a^\alpha$$

$$ds^2 =$$

But now Displacement on B.

$$ds^2 = g_{AB} (N n^\alpha dt + e_A^\alpha d\theta^A) (N n^\beta dt + e_B^\beta d\theta^B)$$

$$ds^2 = N^2 dt^2 + \sigma_{AB} d\theta^A d\theta^B$$

$$\gamma_{ij} dz^i dz^j = N^2 dt^2 + \sigma_{AB} d\theta^A d\theta^B$$

$$(11) \quad Fr = N \sqrt{\sigma} \quad \left| \begin{array}{l} g^{\alpha\beta} \frac{\partial t}{\partial \theta^A} \frac{\partial t}{\partial \theta^B} = g^{tt} = \frac{c^2 (B_{tt})}{B^2} = \frac{\sigma}{N^2} \\ g^{\alpha\beta} n_\alpha n_\beta = N^2 \end{array} \right.$$

$$(12) \quad 16\pi S_g = \int_{\Sigma_2} {}^4K \sqrt{-g} d^4x + 2 \int_{\Sigma_2} K \sqrt{h} dy^3$$

$$\Rightarrow -2 \int_{\Sigma_1} K \sqrt{h} dy^3 - 2 \int_B K \sqrt{-g} d^3z$$

due to  $\epsilon$  timelike surface

Spacelike H.S. Vol hab.  $(h_{ij} = h)$

Timelike H.S. Vol  $\gamma_{ij} \quad |\gamma_{ij}| = -\gamma$  why?

Spacetime Vol.  $g_{AB} \quad |g_{AB}| = -g$

(13) Now Bueck Integral

$$\int_R {}^4K \sqrt{-g} d^4x = \int (3R + K K_{ab} - K^2) N \sqrt{h} dt dy^2$$

$$-2 \int_{\Sigma} (n^\beta \nabla_\beta n^\alpha - n^\alpha \nabla_n n^\beta) d\Sigma_\alpha$$



(14)

Combining all

$$W_{\text{total}} = \int_{t_1}^{t_2} dt \int_{\Sigma_t} (R + k^{ab} k_{ab} - \epsilon^2) \sqrt{-g} N \sqrt{h} d^3y$$

$$= 2 \int_B (R + \nabla_\beta z_\alpha n^\alpha n^\beta) \sqrt{-g} d^3z$$

$$g^{ij} k_{ij} = K = (\nabla_\beta z_\alpha e_i^\alpha e_j^\beta) r^{ij}$$

$$= \nabla_\beta z_\alpha (r^{ij} e_i^\alpha e_j^\beta) = \nabla_\beta z_\alpha (g^{\alpha\beta} + z^\alpha z^\beta)$$

$$= 2 \int_B \nabla_\beta z_\alpha (g^{\alpha\beta} + z^\alpha z^\beta + n^\alpha n^\beta) \sqrt{-g} d^3z$$

from (4) completeness  
Reln

$$= 2 \int_B \nabla_\beta z_\alpha \sigma^{AB} e_A^\alpha e_B^\beta \sqrt{-g} d^3z$$

$$= 2 \int_B \sigma^{AB} K_{AB} \rightarrow 2 \text{ Dim. Ext.}$$

$$= 2 \int_B K \rightarrow \text{Trace}$$

$$= 2 \int_B K \sqrt{-g} d^3z \rightarrow \sqrt{-g} = N \sqrt{\sigma}$$

$$= -2 \int_{t_1}^{t_2} dt \int_{\Sigma_t} K N \sqrt{\sigma} d^3\theta$$

$$\partial V = \Sigma_1 \cup \Sigma_2 \cup B$$

$$\text{On } \Sigma_2 \quad d\Sigma_2 = n_\alpha \sqrt{h} d^3y$$

$$\text{On } \Sigma_1 \quad d\Sigma_1 = -n_\alpha \sqrt{h} d^3y$$

keeping same  $n_\alpha$ .

$$\text{on } B \quad dS_\alpha = \underbrace{-r_\alpha}_{\text{due to } \epsilon} \sqrt{-\gamma} d^3z$$

$$\textcircled{\Sigma_2} \quad 2 \int_{\Sigma_2} (n_\alpha n^\alpha \cancel{\nabla_\beta n^\alpha} + \nabla_\beta n^\beta) \sqrt{h} d^3y$$

$$\rightarrow 2 \int_{\Sigma_2} \kappa \sqrt{h} d^3y$$

$$- 2 \int_{\Sigma_2} \kappa \sqrt{h} d^3y$$

Cancel Out

$\textcircled{\Sigma_1}$  also cancel out

$$\textcircled{B} \quad n_\alpha n^\alpha = 0$$

$$2 \int_B (n^\beta \nabla_\beta n^\alpha - n^\alpha \nabla_\beta n^\beta) \underbrace{(-r_\alpha)}_{\text{due to } \epsilon} \sqrt{-\gamma} d^3z$$

$$= -2 \int_B \nabla_\beta r_\alpha n^\beta n^\alpha \sqrt{-\gamma} d^3z$$

$$16\pi S_g = \int_{t_1}^{t_2} dt \int_{\Sigma_t} \left( R + K^{ab} K_{ab} - K^2 \right) N \sqrt{h} d^3y$$

$$- \int_{\Sigma_t} \left[ 2 K N \sqrt{h} d^2\theta \right]$$

$$\Rightarrow p^{ab} \sim \frac{\partial \mathcal{L}}{\partial \dot{h}_{ab}} \quad \rightarrow \text{Indep. of 3dim } K_{ab}$$

$$h_{ab} \sim \dot{h}_{ab} \sim K_{ab}$$

$\therefore$  Boundary term doesn't contribute to canonical momenta

$$\Rightarrow \mathcal{H} = \underbrace{p^{ab} \dot{h}_{ab}}_{\text{Only Bulk term}} - \underbrace{\mathcal{L}}_{\text{Bulk + Boundary}}$$

$$\underline{\underline{\mathcal{L} - \mathcal{H}}}$$

(1) Till now shift vector doesn't appear.

(2)  $N, N^a \equiv$  Lagrange Multiplier

They are providing the freedom of specifying the coordinate in spacetime.

but  $h_{ab}$  is the dynamical variable.

(3) How to check what is the Canonical/Dyn variable?

Pick the terms in action which depend on time derivatives,

(4) Our action depends on  $k^{ab} k_{ab}, k^2$

$k_{ab}$

But we know  $k_{ab} \propto \dot{x}_{ab}$

$\therefore$  Canonical momentum would be found for conjugate  $k_{ab}$ .

(5) But we also see dependence of action on

$N$   
But not on  $\dot{N}$

$\therefore$  No conjugate momentum associated with  $N$

$\therefore$   $N$  is not dynamical variable as time derivative of  $N$  is not there

(6)  $N$  plays the role of Legendre multiplier

$$\begin{aligned} (7) \quad h_{ab} &\equiv \dot{x}_t h_{ab} = \dot{x}_t (g_{\alpha\beta} e_a^\alpha e_b^\beta) \\ &= (\dot{x}_t g_{\alpha\beta}) e_a^\alpha e_b^\beta \\ &= \left( \frac{\partial t}{\partial x^\alpha} + \frac{\partial t}{\partial x^\beta} \right) e_a^\alpha e_b^\beta \end{aligned}$$

$$t^\alpha = N n^\alpha + \underbrace{N^\alpha e_a^\alpha}_{N^\alpha} \rightarrow \text{push forward}$$

② 
$$= N n^\alpha + N^\alpha$$

~~$N^\alpha$~~

$$ch_{ab} = 2N k_{ab} + \nabla_b N_a + \nabla_a N_b$$

④ if only moving normal then  $h_{ab} = 2N k_{ab}$ .

Now also moving along flow (normal + tangent to H.S.)  
 $N_n$

⑧ Put  $k_{ab}$  in terms of  $h_{ab}$  & find  $p_{ab}$

$$p_{ab} = \frac{\delta(\delta F_g)}{\delta h_{ab}}$$

Only Bulk term would contribute  
 Rec.  $\tilde{k}_{ab} = k_{ab}$  &  $k_{ab}$  appears in Bulk only.

$$\therefore p_{ab} = \frac{\delta(\delta_{\text{Bulk}} F_g)}{\delta h_{ab}}$$

$$ch_{ab} = 2N k_{ab} + \nabla_a N_b + \nabla_b N_a$$

But Bulk term doesn't contain  $N^a$   
 $\therefore$  Take derivative w.r.t.  $K_{ab}$

$$p_{ab} = \frac{\partial (d_{ab} \sqrt{h})}{\partial x^a \partial x^b}$$

$$= \frac{1}{2\sqrt{h}} \frac{\partial}{\partial x^a \partial x^b} \left( \sqrt{h} ({}^3R + k^{ab} k_{ab} - k^2) \right)$$

$$= \frac{\sqrt{h}}{2} \frac{\partial}{\partial x^a \partial x^b} \left( {}^3R + (k_{ab} k_{cd}) \left( \frac{c^a d^b}{h} - \frac{h^{ab} c^d}{h} \right) \right)$$

$$\frac{\partial {}^3R}{\partial x^a \partial x^b} = 0$$

$$= \frac{\sqrt{h}}{2} \left[ \frac{\partial (k_{ef} k_{cd})}{\partial x^a \partial x^b} \right] \left( h^{\frac{e}{a} \frac{d}{b}} - h^{\frac{ef}{cd}} \right)$$

$$= \frac{\sqrt{h}}{2} \left[ \delta^a_b \delta^c_d k_{ef} + k_{ef} \delta^a_b \delta^c_d \right]$$

$$p_{ab} = \frac{\sqrt{h}}{2} (k^{ab} - k^{hab})$$

Express  $k_{ab}$  in terms of  $p_{ab}$  &  $h_{ab}$ .  
through this s.t.  $H(q, p)$

$$H = p_{ab} \dot{h}_{ab} - L$$

$$= \int h (k^{ab} - k^h{}^{ab}) (2Nk_{ab} + \nabla_a N_b + \nabla_b N_a)$$

$$- N ({}^3R + k^{ab} k_{ab} - k^2) \int h$$

$$+ 2 \int_{\text{St}} N^2 k \sqrt{\sigma} d\Theta$$