

- (1) To check if the spacetime is flat or not
- ① coord. transf.
 - ② check if all $R = 0$ then flat.

(2) in (57)
 RHS need not be zero
 if it is not zero then $R_{ik}^j = -\Gamma_{li}^j \Gamma^l_k$ do not possess a $\delta_{0/4}$

\therefore we can't // transf. globally
 But if I have given curve, then I can // transf. along that curve.
 Bcz. given a vector & curve, we can // transf. along that curve always.

③ Th. if spacetime is flat $\Rightarrow R = 0$

Proof. if the spacetime is flat we can always choose inertial coordinate system in which the Γ vanish at all events.

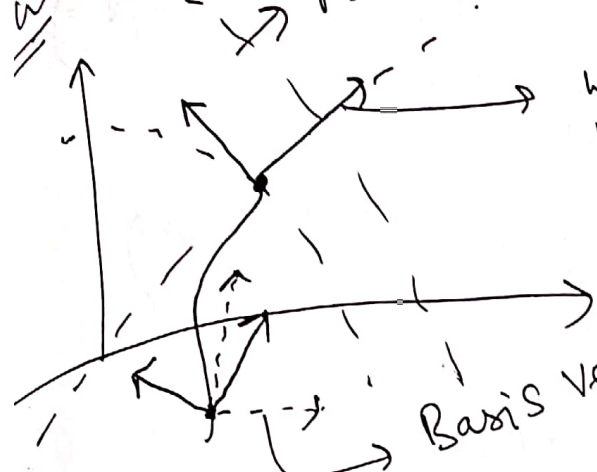
\therefore The derivatives of Γ will also vanish

making $R = 0$

But as R is Tensor & \therefore if it vanish in one coordinate system then it has to vanish in any other coord. system.

\therefore in flat spacetime $R = 0$.

⑥ If $R = 0$ then $\partial_i \Gamma^i_k + \Gamma^i_{li} k^l = 0$ has ~~soln~~ unique soln.
 then spacetime is flat.
 Polar coord.



We can transport everywhere this basis & we get Cartesian grid.
 Cartesian grid would be rotated w.r.t. original basis at every pt.

⑦ If $R \neq 0$ then $\partial_i \Gamma^i_k + \Gamma^i_{li} k^l = 0$ doesn't have soln.
 Basis vectors given.

⑥ & ⑦ are equivalent
 If I can transport globally then I can get Cartesian coordinates globally.
 Transf. to global Cartesian coordinates can be done.

⑥ If I can transp. globally \Rightarrow spacetime is flat.
 Corollary: If $R = 0 \Rightarrow$ spacetime is flat.

⑦ Transf. to global Cartesian coord \Rightarrow spacetime is flat

⑧ If spacetime is flat \Rightarrow transp. to global Cart. coord

⑨ $\nabla_i \nabla_j$ covariant derivative $\nabla_i \nabla_j v^k - \nabla_j \nabla_i v^k = (\nabla_i g_{jk} - \nabla_j g_{ik}) v^k \neq 0$
 does not commute like $\partial_i \partial_j$.
 i.e.

$$\textcircled{10} \nabla_i (\nabla_j v^k) = \partial_i (\nabla_j v^k) + \Gamma_{xi}^k v^x - \Gamma_{ij}^l \nabla_l v^k$$

$$= \partial_i \partial_j v^k + \partial_i (\Gamma_{mj}^k v^m) + \Gamma_{ei}^k (\partial_j v^e + \Gamma_{mj}^e v^m) - \Gamma_{ij}^l (\partial_e v^k + \Gamma_{ml}^k v^m)$$

$$(\nabla_i \nabla_j - \nabla_j \nabla_i) v^k = \partial_i (\Gamma_{mj}^k v^m) - \partial_j (\Gamma_{mi}^k v^m) + \Gamma_{ei}^k (\partial_j v^e + \Gamma_{mj}^e v^m) - \Gamma_{ej}^k (\partial_i v^e + \Gamma_{mi}^e v^m)$$

$$= (\partial_i \Gamma_{mj}^k) v^m + \cancel{(\Gamma_{mj}^k) \partial_i v^m} - (\partial_j \Gamma_{mi}^k) v^m - \cancel{(\Gamma_{mi}^k) \partial_j v^m} + \Gamma_{ei}^k \cancel{\partial_j v^e} + \Gamma_{ei}^k \Gamma_{mj}^e v^m - \Gamma_{ej}^k \cancel{\partial_i v^e} - \Gamma_{ej}^k \Gamma_{mi}^e v^m$$

All terms sym in i & j would cancel out

$$= (\partial_i \Gamma_{mj}^k - \partial_j \Gamma_{mi}^k) v^m + \cancel{\Gamma_{mi}^k \partial_j} - \cancel{\Gamma_{mi}^k} (\Gamma_{ei}^k \Gamma_{mj}^e - \Gamma_{mi}^e \Gamma_{ej}^k) v^m$$

$$= (\partial_i \Gamma_{mj}^k - \partial_j \Gamma_{mi}^k + \Gamma_{ei}^k \Gamma_{mj}^e - \Gamma_{mi}^e \Gamma_{ej}^k) v^m$$

$$= R^k_{mij} v^m$$

$$\boxed{(\nabla_i \nabla_j - \nabla_j \nabla_i) v^k = R^k_{mij} v^m}$$

$$(\partial_i \partial_j - \partial_j \partial_i) v^k = 0 \rightarrow \text{see } \textcircled{57}$$

th: R^k_{mij} is the Tensor

Proof

$\nabla_i \nabla_j v^m$ is the ~~tensorial~~ tensorial obj.

$\therefore (\nabla_i \nabla_j - \nabla_j \nabla_i) v^m$ is ~~covariant~~ tensor

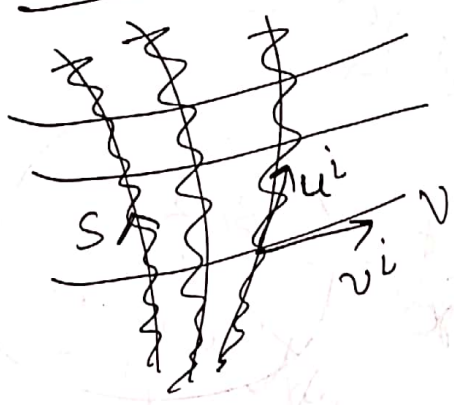
As v^m is a vector

$\therefore R^k_{mij}$ has to be tensor

(12) As R^k_{mij} is a Tensor
 if it vanishes in one frame, it will vanish
 in all other frames. see (3)

(13) Just like we have 2nd derivative of curve being
 Curvature
 Here also 2nd derivative of metric is curvature.

(14) Geodesic Deviation



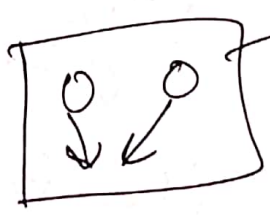
} Geodesic
 s : tells where on the
 geodesic I am
 v : picks up on which
 geodesic I am
 $\therefore s$ & v will tell the given
 location of plane.

\therefore Any point on geodesic
 can be given as $x^i(s, v)$

(15) $u^i = \frac{\partial x^i}{\partial s}$ as now x^i depends on s & $v \therefore \frac{\partial x^i}{\partial s}$

(16) $v^i = \frac{\partial x^i}{\partial v}$: Tells the deviation B/w Geodesic

(17) If I move in u^i how will v^i change?



as Both follow geodesics
 But by princ. of Eq. Both
 should have followed same
 path for. of their prop?

Only valid in small
 res.

(18) In Newtonian


$$v^\alpha = \frac{\partial x^\alpha}{\partial t}$$

$$\frac{\partial^2 v^\alpha}{\partial t^2}$$

= Acc. of sep. vector =

$$\frac{\partial v^\alpha}{\partial t} = \text{vel. of sep vector}$$

= But vel. changes in each frame in Gal. Trans. \therefore Acc. is the qty we are interested in.

Rec. in plane paper 
 ~~$\frac{\partial^2 v^\alpha}{\partial t^2} = 0$~~
 ~~$\frac{\partial v^\alpha}{\partial t} \neq 0$~~ But it is plane of paper is what is $\frac{\partial^2 v^\alpha}{\partial t^2}$ is what is $\frac{\partial v^\alpha}{\partial t}$ We are interested in this qty. Not $\frac{\partial v^\alpha}{\partial t}$.

(19)
$$\frac{\partial^2 v^\alpha}{\partial t^2} = \frac{\partial}{\partial v} \left(\frac{\partial^2 x^\alpha}{\partial t^2} \right) = - \frac{\partial}{\partial v} \frac{\partial \phi}{\partial x^\alpha} = - v^\beta \left(\frac{\partial^2 \phi}{\partial x^\beta \partial x^\alpha} \right)$$

(1, 1) $\therefore dx^\alpha = dx_\alpha$

Doubt
 2nd derivative of Potential.

(20) Tides Produced on Earth by Sun & Moon are of Equal Mag.
 Even though Sun's Grav. force on Earth \gg Moon's on Earth



But why water is attracted in one direction & repelled in other?

This is due to the diff. of the force exerted at centre of Earth & water.

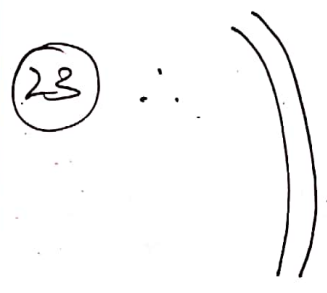
$\therefore F \propto \frac{1}{r^2}$ $T_f = \int dF \propto \frac{d}{r^3}$ \therefore Tidal forces go by $\frac{1}{r^3}$
 But Now $\frac{M_s}{3} \approx M_m \therefore$ Tidal forces

(22)
$$-\nu^\beta \frac{\partial^2 \phi}{\partial x^\beta \partial x^\beta}$$

As Tidal forces are (Grad. of forces) x Distance
 equivalent to

$$\frac{\partial^2 v^\alpha}{\partial t^2} = -\nu^\beta \left(\frac{\partial^2 \phi}{\partial x^\beta \partial x^\alpha} \right)$$

This tells how grav. force is changing from place to place.
 (Grad. in β direct) x Direction in β dir.



(23) Two infinitesimal separated geodesic then
 Take force on one geodesic
 Take force on other geodesic
 Take Diff & Mult. by distance
 we get acc. of geodesics towards one other.

(24) $\frac{\partial^2 \phi}{\partial x^\beta \partial x^\alpha} \equiv$ This tells how grav. force is changing from place to place.

Grav force \equiv Grad. of Pot $\equiv \Gamma$
 \therefore we should see $\partial_i \Gamma$

(25) We want to know acc. of sep. of geodesic.

~~$u^i \nabla_i v^j = \text{Acc.}$~~
 $u^i \nabla_i v^j =$ change in v^j along u^i
 $(u^i \nabla_i)(u^j \nabla_j v^k) = D^2 v^k \equiv$ Acc. of v^k along u^i

(26) $\frac{\partial}{\partial u^i} \nabla_i v^k = v^i \nabla_i u^k$

$u^i \nabla_i = \frac{\partial}{\partial x^i}$

$\frac{\partial}{\partial x^i} \left(\frac{\partial x^k}{\partial u^i} \right) = \frac{\partial}{\partial u^i} \frac{\partial x^k}{\partial x^i}$

~~Proof?~~

(27) $u^i \nabla_i (u^j \nabla_j v^k) = u^i \nabla_i (v^j \nabla_j u^k)$
 $= u^i v^j \nabla_i \nabla_j u^k$

$+ u^i \nabla_j u^k \nabla_i v^j$
 $= u^i v^j \nabla_i \nabla_j u^k$
 $+ (\nabla_j u^k) v^i \nabla_i u^j \quad \text{--- (1)}$

$(\nabla_j u^k) v^i \nabla_i u^j = v^i (\nabla_i u^j) \nabla_j u^k$
 $= v^i (\nabla_i (u^j \nabla_j u^k) - (\nabla_i \nabla_j u^k) u^j)$

But $u^j \nabla_j u^k = 0$ Geod. Eqn.
 $= -v^i u^j \nabla_i (\nabla_j u^k)$
 $= -v^i u^j \nabla_i \nabla_j u^k$

Putting in (1)

$= u^i v^j \nabla_i \nabla_j u^k - v^i u^j \nabla_i \nabla_j u^k$
 $\geq u^i v^j \nabla_i \nabla_j u^k - v^j v^i \nabla_j \nabla_i u^k$

$$= v^i u^j (\nabla_i \nabla_j - \nabla_j \nabla_i) u^k \quad \text{By (10)}$$

$$D^2 v^k = v^i u^j R^k_{lij} u^l$$

↳ Geodesic Deviation Acc.

(28) In Newtonian Limit — see L. (19) (5)
 u^l, u^i Only zeroth comp. will contribute

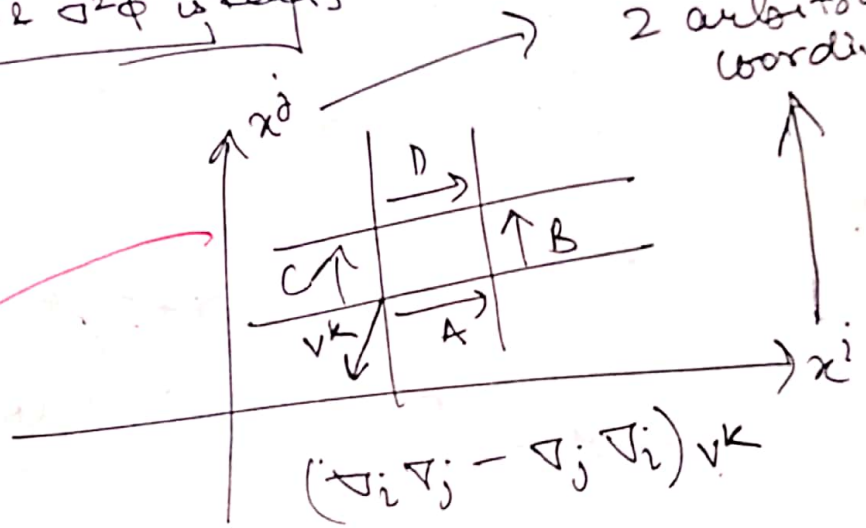
$$R_{\alpha\beta\gamma\delta} \approx \partial_\alpha \partial_\beta \phi \quad \text{for } R_{\alpha\beta\gamma\delta} \Rightarrow g_{00} = (1 + 2\phi)$$

$$g_{\alpha\beta} = \delta_{\alpha\beta}$$

as in Newton $\nabla^2 \phi = 4\pi G \rho$
 ∴ from struct. of R we can tell that we can contract it with other object in fields & get $R_{\alpha\beta\gamma\delta} g^{\alpha\beta} = g^{\alpha\beta} \partial_\alpha \partial_\beta \phi$ & $\nabla^2 \phi$ is ready

2 arbitrary coordinates

(29) See Ch-5 (7)
 Lec (10) (10)



We would see vectors being same but physically they are diff.

$$A \rightarrow B \quad \nabla_j \nabla_i v^k$$

$$C \rightarrow D \quad \nabla_i \nabla_j v^k$$

$$(\nabla_j \nabla_i - \nabla_i \nabla_j) v^k = \text{Diff in } v^k \text{ when 2 paths are taken}$$

$$= R^k_{mij} v^m$$

$$= \text{Depends on Curvature}$$

$$\Delta v^a = \frac{1}{2} (R^a_{bcd}) v^b v^c dx^d$$

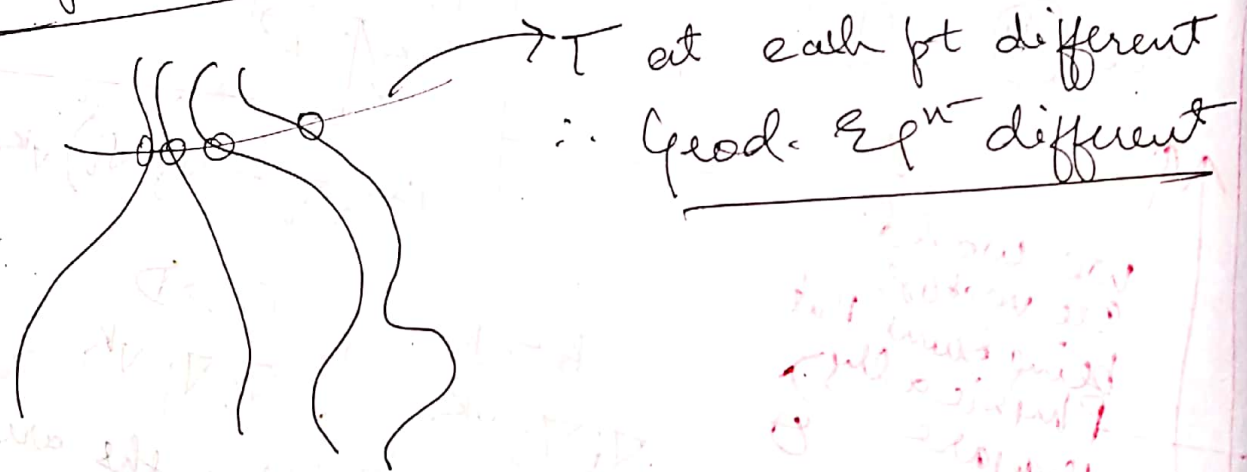
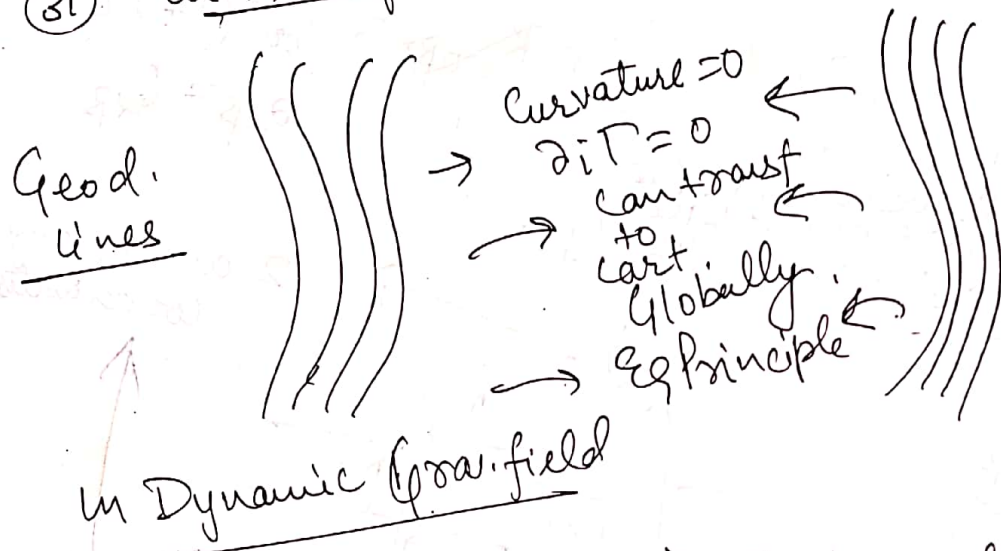
(20) for $1/gm$.

$$\Delta v^a = -\frac{1}{2} R^a{}_{bcd} v^b \Delta \sigma^{cd}$$

↑
Area enclosed by the loop.

Since all other qty are tensors, $R^a{}_{bcd}$ is a tensor as long as we are dealing with infinitesimal region in Uniform Grav.

(31) in Acc frame



(32) Properties of R

$$R^k{}_{ija} = \partial_i \Gamma^k{}_{ja} - \partial_j \Gamma^k{}_{ia} - \Gamma^p{}_{ia} \Gamma^k{}_{jp} + \Gamma^p{}_{ja} \Gamma^k{}_{ip}$$

$$R_{mija} = g_{mk} R^k{}_{ija}$$

(33) Around Local inertial frame at any pt.

~~g_{ij}~~ $\Gamma_{jk}^i = 0$
 $g_{ab} = \eta_{ab}$

But $\partial_l \Gamma_{jk}^i \neq 0$ Bec. Earlier we said in L.I.f. all $g_{ab}|_p = \eta_{ab}$
 $\partial_l g_{ab}|_p = 0$
 But $\partial_i \partial_l g_{ab}|_p \neq 0$ except 20.

(34) If $g_{ab} = \eta_{ab}$ globally

then $\partial_l g_{ab} = \partial_l \eta_{ab} = 0$ & $\partial_i \partial_l g_{ab} \neq 0$
 But here we have to compute $(\partial_l g_{ab})|_p = 0$
 & similarly $\partial_i \partial_l g_{ab}|_p \neq 0$.

(35) ∴ Curvature \exists in local inertial frame.
 ∴ There is diff. B/w local I.f. & BOX

(36) $R_{mija} = \partial_i \Gamma_{ja}^k - \partial_j \Gamma_{ia}^k$
 $= \partial_i (g_{mk} \Gamma_{ja}^k) - \partial_j (g_{mk} \Gamma_{ia}^k) - (\partial_i g_{mk}) \Gamma_{ja}^k + (\partial_j g_{mk}) \Gamma_{ia}^k$

$= \partial_i \Gamma_{mja} - \partial_j \Gamma_{mia}$
 $= \frac{1}{2} \left[\partial_i (-\partial_m g_{ja} + \partial_j g_{am} + \partial_a g_{mj}) - \partial_j (-\partial_m g_{ia} + \partial_i g_{am} + \partial_a g_{mi}) \right]$
 $= \frac{1}{2} \left[\partial_i (-\partial_m g_{ja} + \partial_a g_{mj}) - \partial_j (-\partial_m g_{ia} + \partial_a g_{mi}) \right]$
 $= \frac{1}{2} \left[-\partial_i \partial_m g_{ja} + \partial_i \partial_a g_{mj} + \partial_j \partial_m g_{ia} - \partial_j \partial_a g_{mi} \right]$

(37) Originally we had
 $R_{abcd} = -R_{abdc}$

Now

$$R_{abcd} = -R_{bacd}$$

from (36)

(38) $R_{abcd} = R_{cdab}$ from (36)

(39) Though we are proving it in L.I. frame
 But they ~~was~~ properties would hold
 in every frame.

Because R_{abcd} are Tensors.

and hence when $R_{a'b'c'd'} = \frac{\partial x^a}{\partial x'^a} \frac{\partial x^b}{\partial x'^b} \frac{\partial x^c}{\partial x'^c} \frac{\partial x^d}{\partial x'^d} R_{abcd}$

(40)

$$R_{a'b'd'e'} = \frac{\partial x^a}{\partial x'^a} \frac{\partial x^b}{\partial x'^b} \frac{\partial x^c}{\partial x'^c} \frac{\partial x^d}{\partial x'^d} R_{abcd}$$

$$= \frac{\partial x^a}{\partial x'^a} \frac{\partial x^b}{\partial x'^b} \frac{\partial x^d}{\partial x'^d} \frac{\partial x^c}{\partial x'^c} R_{abdc}$$

$$= - \frac{\partial x^a}{\partial x'^a} \frac{\partial x^b}{\partial x'^b} \frac{\partial x^d}{\partial x'^d} \frac{\partial x^c}{\partial x'^c} R_{abcd}$$

$$R_{a'b'd'e'} = -R_{a'b'd'e'}$$

\therefore Valid in Any frame

$ds^2 = \int g_{ab} dx^a dx^b$
 L.I.f.
 $g_{ab} = g_{ba}$
 $ds^2 = \int g_{ab} dx^a dx^b$
 Tensor
 \therefore Valid in Any frame

(40) $R_{abcd} + R_{adbc} + R_{acdb} = 0$

$$R_{a[bcd]} = 0$$

(41) $R_{abcd} + R_{adbc} + R_{acdb}$ ~~is~~

↑
This is Totally Antisym. Tensor

Proof.

~~$-R_{abdc} + R_{bcad} + R_{dbac}$~~ ~~$-R_{abdc} - R_{bcda} - R_{bdca}$~~

~~$-R_{abdc} + R_{bcad} + R_{bdca}$~~

~~$-R_{badc} + R_{acba} + R_{adcb}$~~

$R_{abdc} + R_{acbd} + R_{adcb}$

⊙

$R_{abcd} + R_{adbc} + R_{acdb}$
 $= R_{bacd} + R_{bdac} + R_{cbda}$
 $= - (R_{abcd} + R_{acdb} + R_{adbc})$

(42) How many independent comp from $L = 7$

(34)

Excess Dof. $\frac{N^2(N^2-1)}{12} = \text{No. of Ind. comp.}$

As in $g_{ab} = n_{ab}$ Exc. dof = 6 in 4D which is equal to Dof used for L.T.

- $g_{ab} = n_{ab}$ 10 cond
 - $\partial_j g_{ab} = 0$ 40 cond
 - $\partial_i \partial_j g_{ab} = 0$ 100 cond
- 16 par
40 par.
80 par

$\therefore 20 = \frac{N^2(N^2-1)}{2}$ such conditions were left which were not followed

(43) R_{abcd}

let pair take M ind. values.

\therefore as $R_{abcd} = R_{edab}$ (Sym)

$$M+1 \binom{M}{2} = \frac{M(M+1)}{2}$$

$M = N \binom{N}{2}$ as $R_{abcd} = -R_{abdc}$

(44) $R_{a[bcd]} = 0$

As this is totally A.S. \therefore if $R_{1123} = 0$ any 2 indices same $\Rightarrow R = 0$

\therefore we have to take all indices different.

\therefore Independent condⁿ will be given when all indices are diff.

see ch-6
(32)

$N \binom{N}{4}$ i.e. $N \binom{N}{4}$ terms can be written in other terms

(45) Ind. Comp = $M+1 \binom{M}{2} - N \binom{N}{4}$

$$= \frac{N \binom{N}{2} (N \binom{N}{2} + 1)}{2} - \frac{N(N-1)(N-2)(N-3)}{4 \cdot 3 \cdot 2}$$

$$= \frac{N(N-1)}{2} \left(\frac{N(N-1)+2}{8} \right) - \frac{N(N-1)(N-2)}{24}$$

$$= \frac{3N^2 - 3N + 8 - N^2 + 5N}{3} \left(\frac{N(N-1)}{8} \right)$$

159

$$= \frac{2N^2 + 2N}{3} \left(\frac{N(N-1)}{8} \right)$$

$$= \frac{N^2(N+1)(N-1)}{12}$$

$$= \frac{N^2(N^2-1)}{12}$$

(46) In $N=4$
 R has 20 Ind. Comp.

(47) In Newtonian
 R is 3×3 Sym. Matrix
 \therefore 6 Ind. Comp.

In 2D

1 Ind Comp

(48) Rijke

Th Only contraction on
 See Ch-(6) 34, 35

if K is non trivial.
 $R = R_{jkl} = R_{kjl}$
 $R_{jl} = R_{kj}$

(49) $g^{ik} R_{jke} = R_{je} \equiv$ Ricci Tensor
 $R = R_{je} g^{ie}$ 10 Ind Comp

(50) R_{je} is Sym. in j, e
 Proof: $R_{je} = g^{ik} R_{jke} = g^{ik} g_{im} (R_{jle}^m - R_{jlm}^e + R_{okj}^m - R_{okl}^e)$

(51) $G_{ab} = R_{ab} - \frac{1}{2} g_{ab} R =$ Einstein Tensor
 \hookrightarrow Sym in a & b .

① Bianchi Identity
 $\nabla_i R^a_{bcd} + \nabla_c R^a_{bdi} + \nabla_d R^a_{bic} = 0 \quad \text{--- (1)}$

Proof
 $R^a_{bcd} = \partial_c \Gamma^a_{bd} - \partial_d \Gamma^a_{bc} + \Gamma^a_{ec} \Gamma^e_{bd} - \Gamma^a_{ed} \Gamma^e_{bc}$

$$\begin{aligned} \nabla_i R^a_{bcd} &= \nabla_i (\partial_c \Gamma^a_{bd}) - \nabla_i (\partial_d \Gamma^a_{bc}) \\ &+ \Gamma^e_{bd} \nabla_i \Gamma^a_{ec} + (\nabla_i \Gamma^e_{bd}) \Gamma^a_{ec} \\ &- \Gamma^e_{ed} \nabla_i \Gamma^a_{bc} - \Gamma^e_{bc} \nabla_i \Gamma^a_{ed} \end{aligned}$$

But in local inertial frame

$$g_{ij} = \eta_{ij}$$

$$\partial_i g_{ab} = 0 \Rightarrow \Gamma^i_{jk} = 0$$

$$\begin{aligned} \therefore \nabla_i R^a_{bcd} &= \nabla_i (\partial_c \Gamma^a_{bd}) - \nabla_i (\partial_d \Gamma^a_{bc}) \\ &= \partial_i (\partial_c \Gamma^a_{bd}) - \partial_i (\partial_d \Gamma^a_{bc}) \end{aligned}$$

from this (1) can be easily proved.

② Raising b in R^a_{bcd}

Doubt In R^a_{bcd} if raising b in Antisym. there can be a sign flip.

In R^{ab}_{cd} we have to raise b in Γ which is not easy.

③ $\nabla_i R^{ab}_{cd} + \nabla_c R^{ab}_{di} + \nabla_d R^{ab}_{ic} = 0$

$\Rightarrow (\nabla_i R^{ab}_{cd}) g^c_a = (\nabla_i R^{ab}_{cd} g^c_a) - (\nabla_i g^c_a) R^{ab}_{cd}$
 $\parallel 0$

$\nabla_i (R^{ab}_{cd} g^c_a) = \nabla_i R^b_d \rightarrow \delta^i_b$

$\Rightarrow g^i_b \nabla_i R^b_d = g_{bk} g^{ki} \nabla_i R^b_d$
 $= g_{bk} \nabla^k R^b_d$
 $= \nabla_b R^b_d$

~~$g^a_b = \delta^a_b$~~
 ~~$g^a_b = g^{am} g_{mb} = \delta^a_b$~~

~~$\nabla_c (R^{ab}_{di}) = \nabla_c (R^{ab}_{di} g^c_a) - (\nabla_c g^c_a) R^{ab}_{di}$~~
 ~~$= \nabla_c (R^{ab}_{di} g^c_a) - \frac{\partial_c (\sqrt{-g} g^c_a)}{\sqrt{-g}} R^{ab}_{di}$~~
 ~~$+ \frac{1}{2} (\partial_c g_{em}) g^{em} R^{ab}_{di}$~~

$(\nabla_c R^{ab}_{di}) g^i_b = (\nabla_c R^{ab}_{di} g^i_b) - (\nabla_c g^i_b) R^{ab}_{di}$

$\hookrightarrow R^{ba}_{id}$
 $g^c_a \nabla^a_c R^d = g_{ak} g^{kc} \nabla_c R^a_d = g_{ak} \nabla^k R^a_d$
 $= \nabla_a R^a_d$

$g^c_a (\nabla_d R^{ab}_{ic}) = -g^c_a (\nabla_d R^{ab}_{ci}) = -\left[\nabla_d (R^{ab}_{ci} g^c_a) - \nabla_d (g^c_a) R^{ab}_{ci} \right]$

$g^i_b (\nabla_d R^b_i) = -\nabla_d R^b_i + (\nabla_d g^i_b) R^b_i \Rightarrow -\nabla_d R^b_i$

$$\therefore \nabla_b R^b_d + \nabla_a R^a_d - \nabla_d R = 0$$

But R is scalar $\therefore \nabla_d R \Rightarrow \partial_d R$

$$2 \nabla_a R^a_d - \nabla_d R = 0$$

$$\nabla_a R^a_d - \frac{1}{2} \nabla_d R = 0$$

$$\Rightarrow \nabla_b R^b_d - \frac{1}{2} \delta^b_d (\nabla_b R) = 0$$

$$\Rightarrow \nabla_b R^b_d - \frac{1}{2} \nabla_b (\delta^b_d R) = 0$$

$$\Rightarrow \nabla_b \left[R^b_d - \frac{\delta^b_d R}{2} \right] = 0$$

But from Th. $\delta^b_d = g^b_d$

$$\Rightarrow \nabla_b \left[R^b_d - \frac{g^b_d R}{2} \right] = 0$$

$G^b_d \equiv$ Einstein Tensor

(4) Divergence of $G^b_d = 0$

$$\therefore \nabla_b G^b_d = 0 \Rightarrow \boxed{\nabla^k G_{dk} = 0}$$

Divergence of Einstein Tensor = 0

(5) ~~Doubt~~

As G^b_d is sym. \therefore Divergence of Einstein Tensor on both indices = 0

(6) Field Equⁿ

$$R^a_{bed} \partial_i \Gamma = \partial_i \partial_a \phi \rightarrow \text{from Geodesic Deviation Acc.}$$

We can get $\partial_i \partial_a \phi$ by R^a_{bed} by contracting

and then ~~we~~
 we want field eqn which will generalize
 $\sum \phi = 4\pi p q \therefore$ in GR, field eqn R_{abcd} should be there.

⑦ $A = -m \int d\tau - q \int A_i dx^i - \frac{1}{16\pi} \int F_{ab} F^{ab} d^4x$

\uparrow free action for particle
 \uparrow How charge is coupling to given External A_i field
 \downarrow free action for field
 How the field changes given j^a

x^i
 \uparrow
 A_j, ϕ, x^α : Dependent variable

$L_f(A_j, \partial_k A_j) \equiv L_f(\phi, \partial_i \phi) \equiv L(x^\alpha, \dot{x}^\alpha)$

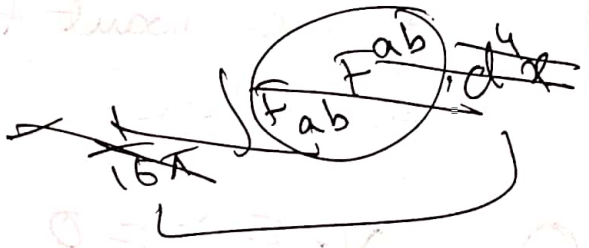
As A is q.I. $\rightarrow L_f(F_{ab}) \rightarrow$ Due to L-I.
 $L_f = F_{ab} F^{ab}$ or $\epsilon^{abcd} F_{ab} F_{cd}$

$\rightarrow A = \frac{1}{16\pi} \int F_{ab} F^{ab} d^4x$

$L_f(\phi, \partial_i \phi) = \frac{\partial_i \phi \partial^i \phi}{2} - U(\phi)$

⑧ Going with flow for Grav.

$A = -m \int d\tau - q \int (R_{ij}/\phi) dx^i$
 $- \int L_{grav} d^4x$



But we have already seen this leads to wrong result : Light Bending, Two masses attraction.

⑨ Matter: Anything other than gravity

$$A_m = \int L_m(\phi, \partial_i \phi) d^4x$$

↑
 x, A_j → Odd. Deriv.

in EM
 By ⑦

Suppose there is massive particle around just + EM field

$$L_m(A_j, \partial_j A_j) = \frac{F_{ab} F_{ab}}{16\pi}$$

$$A_m = \int \frac{F_{ab} F_{ab}}{16\pi} d^4x$$

⑩ $A_m = \int L_m(\phi, \nabla_i \phi) \sqrt{-g} d^4x$ — ①

See L-9 ③② $\hookrightarrow \equiv L_m(\phi, \partial_i \phi)$ as $\nabla_i \phi = \partial_i \phi$
 $\sqrt{g_{ab} dx^a dx^b} = L(\dot{x}^a, x^a)$
 are already incorporated in this.

~~Doubt~~

$$-m \int ds - q \int A_i dx^i$$

⑪ We can take ① & everything will work out
 But
 If we want to start with EOM & then generalize.

~~Doubt~~

⑫ $\nabla_i F^{ik} = 0$ ③

$$\begin{aligned} \partial_i F^{ik} &= \partial_i (\partial^i A^k - \partial^k A^i) \\ &= \square A^k - \partial_k \partial_i A^i = 4\pi J^k \end{aligned}$$

RHS = 0 in free space.
 Using Gauge (Lorentz) $\partial_i A^i = 0$

Never going to find soln of this Eqn so it is stupid to solve for this without imposing Gauge Condition

$$\square A = 0$$

By (11)

$$\square A^k = \partial_i \partial^i A^k = 0$$

Should generalize to

$$\square A^k = \nabla_i \nabla^i A^k = 0$$

(14) But we don't get this

$$\nabla_i F_{ij} = 0$$

$$\nabla_i (\nabla^i A^j - \nabla^j A^i) = 0$$

$$\nabla_i \nabla^i A^j - \nabla_i (\nabla^j A^i) = 0$$

$$\square A^j - \nabla_i (\nabla^j A^i) = 0$$

↑
Don't commute like $\partial_i \partial^j$

$$(\nabla_i \nabla_j - \nabla_j \nabla_i) A^i = R^i_{kij} A^k = R_{kj} A^k$$

as this is contraction on 1 & 3

$$\therefore R^i_{kij} = R_{kj}$$

$$\square A^j - \nabla^j \nabla_i A^i - R^j_k A^k = 0$$

Using gauge Lorenz condition $\nabla_i A^i = 0$

$$\square A^j - R^j_k A^k = 0$$

↑
Too small to be detected

(15) \therefore correct approach is to modify action & then obtain EOM.

(16) $A_m = \int L_m(g^{ab}, \Phi) \sqrt{-g} d^4x$

$\Rightarrow L_m(x^i, \partial_\mu x^i)$

~~$\Phi = \Phi(x)$~~
 ~~$= \partial_i \phi$~~

ϕ : generic symbol.

for all Exp. purpose: Minimal coupling works.

(17) why not?

$A_m = \int L_m(g^{ab}, \Phi) \sqrt{-g} d^4x$

Explicit coupling to curvature can never be determined by Princ. of Eq.

\Rightarrow In flat spacetime $R=0$ & get back same Lag.

Principle of minimal coupling

Eg for scalar field $A_m = \int (\partial_a \phi \partial_b \phi R^{ab} + \partial_a \phi \partial^a \phi)$

These things cannot be excluded by Princ. of Eq.

Principle of Eq. is local principle which works in infinite small region. But here curvature can be there & \therefore coupling to curvature can never be determined

(18) $A_{total} = \int L_m(g^{ab}, \Phi) \sqrt{-g} d^4x + \int L_{grav}(g^{ab}) \sqrt{-g} d^4x$

just like $L(A_j, \partial_k A_j)$
 $\Rightarrow L(g^{ab}, \partial_k g^{ab})$
 But there is no way I can construct scalar from this

we need L_{grav} for same reason we need EM field

19 Dynamical Variable ϕ

$\therefore L(\phi, \partial_i \phi) \equiv L(g_{ab}, \partial_i g_{ab})$
 just as $L(A_j, \partial_i A_j) \equiv L(F_{ab})$

Why can't construct a scalar from g_{ab} ; $\partial_k g_{ab}$?
 $g_{ab} + g_{cd} \partial_k g_{ab} \partial_k g_{cd} \rightarrow$ scalar?

20 2nd Derivatives of g_{ab} is Req.

$L(q, \dot{q}, \ddot{q})$

Non-trivial scalar can be made.

as going to initial local frame
 $g_{ab} = \eta_{ab}$
 $\partial_i g_{ab} = 0$
 \therefore No non-trivial

which is bad

\therefore 2nd order DE will be obtained
 But for some reasons we get 2nd order DE

how δg_{ab} come if we are δ w.r.t g_{ab}

we get 2nd order DE

21

$\delta A_{tot} = \int \frac{\delta \mathcal{L}_m}{\delta g_{ab}} \delta g_{ab} d^4x + \int \frac{\delta \mathcal{L}_{grav}}{\delta g_{ab}} \delta g_{ab} d^4x = 0$

w.r.t. g_{ab}

just like we did to obtain field Eq.
 w.r.t. A_j
 just like in us acting External source in EM
 $\partial_i F_{ik} = \mu_0 j_k$

Why T_{ab} is the source?
 as T_{ab} is coming from a matter & as grav. field is affected by matter $\therefore T_{ab}$ is the source.

$\Rightarrow \boxed{E_{ab} = \frac{T_{ab}}{2}}$ EOM

22

From matter Action we are picking T_{ab} which is acting as source.

as Action has to be L.I. or scalar.

23

$\delta A_m = \frac{1}{2} \int \delta g_{ab} T_{ab} \sqrt{-g} d^4x$

Properties of T_{ab}

- 1) T_{ab} is 2 Rank tensor as it is obtained from Action $\int T_{ab} \delta g_{ab}$
- 2) T_{ab} is Sym as

(25) in SR

$$\partial_a \tau^a_b = 0 \Rightarrow \nabla_a \tau^a_b = 0$$

Now we want to prove $\nabla_a \tau^a_b = 0$ though we don't know what τ^a_b is from (24)

(26)

Under $x^a \rightarrow x^a + \epsilon^a$

$$\delta g^{ab} = \nabla^a \epsilon^b + \nabla^b \epsilon^a$$

(27)

$$\delta A_M = \frac{1}{2} \int \sqrt{-g} d^4x T_{ab} (\nabla^a \epsilon^b + \nabla^b \epsilon^a) + \delta A_f$$

Net Change $\delta A_M = \left(\frac{\delta A_M}{\delta \phi} \right) \delta \phi + \left(\frac{\delta A_M}{\delta g^{ab}} \right) \delta g^{ab}$

as T_{ab} is sym

We were already changing about δg_{ab} Now x^i ? How?

under $x^a \rightarrow x^a + \epsilon^a$

$$\int \sqrt{-g} d^4x T_{ab} \nabla^a \epsilon^b$$

$$= \int \sqrt{-g} d^4x \nabla_a (T^a_b \epsilon^b) - \int \sqrt{-g} d^4x \epsilon^b \nabla_a T^a_b + \delta A_f$$

(28)

$$\delta(L\sqrt{-g}) = L \left(-\frac{g_{ab}}{2} \delta g^{ab} \sqrt{-g} \right) + \sqrt{-g} \delta L$$

$$= L \left(-\frac{g_{ab}}{2} (\nabla^a \epsilon^b + \nabla^b \epsilon^a) \sqrt{-g} \right) + \sqrt{-g} \delta L$$

$$= L \left(-g_{ab} \nabla^a \epsilon^b \sqrt{-g} \right) + \sqrt{-g} \delta L$$

$$= -L \nabla_a \epsilon^a \sqrt{-g} + \sqrt{-g} \delta L$$

$$= -\sqrt{-g} (L \nabla_a \epsilon^a + \epsilon^a \nabla_a L) =$$

(29)

$$\delta L = \bar{L}(x) - L(x)$$

change in functional form

$$= \bar{L}(x + \epsilon) - L(x)$$

$$= \bar{L}(x) + \epsilon^a \nabla_a \bar{L} - L(x)$$

L is scalar $\therefore L(x) = \bar{L}(x)$

(30)

$$\delta(L\sqrt{-g}) = -\sqrt{-g} \nabla_a (L \epsilon^a)$$

why L is scalar?

(31) $\int \delta A_m = \int \delta(L \sqrt{g}) d^4x$

as $A_m = \int L \sqrt{g} d^4x$
 where L is scalar

$\int \delta A_m = -\sqrt{g} \int \nabla_a (L \eta^a) d^4x$

I can always choose this \uparrow

on surface if η^a vanishes. $\delta A_m = 0$
 \rightarrow as η^a is in my hand: $\delta A_m = 0 \neq \eta^a$
 $\therefore \nabla_a \eta^a = 0$
 'is identity'

(32) Using (27)
 RHS st term vanishes
 $\delta A_m = 0$

$\therefore \nabla_a \eta^a = 0 \iff$ EOM \rightarrow how?

(33) In EM
 when I make coordinate transfⁿ
 $x^a \rightarrow x^a + \eta^a$
 then my A_j will change
 and as I am varying w.r.t A_j
 δA_m will pick up extra term

Doubt?

In Landau

(34) We are not considering this \rightarrow considering $\delta A_j = 0$

\rightarrow as log is assumed to be Lorentz invariant

35

$$\nabla_a T^a_b = 0$$



EOM

~~BOOK~~ (213)

T^a_b is of a particle

T^a_b is of a field

USK $\nabla_a T^a_b$ goes to conservation of both Energy & Momentum.

36

from $\nabla_a T^a_b = 0$

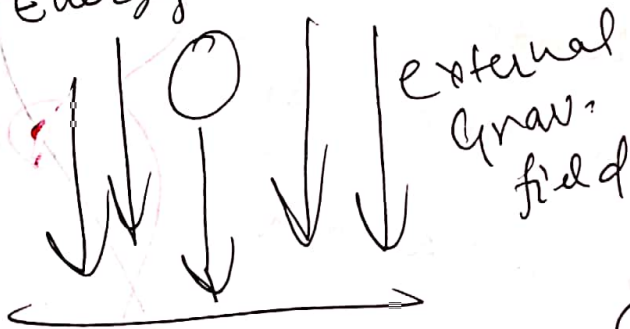
Conservation law cannot be obtained if $\partial_b g_{ac} \neq 0$

from this one can obtain

see $\nabla_a (T^a_b \epsilon^b) = 0$

\therefore Energy-Mom. Tensor is not a conserved qty.

Energy of Ball does not remain constant.



$\nabla_a T^a_b$ is not a conservation law in curved spacetime (particle trajectory) *earlier SA. = $\int dt = 0$ (given)*

37

$$A_m = -m \int ds = -m \int \sqrt{g_{ab} dz^a dz^b}$$

$$z^a(s) = \text{Traj}$$

$$SA_m = -\sum_a m_a \int \frac{1}{2} (\delta g_{ab}) u^a u^b ds$$

$$= \sum_a \frac{m_a}{2} \int u_a u_b \delta g^{ab} ds = \frac{1}{2} \int \rho u_a u_b \sqrt{-g} dx^4$$

$$0 = \text{B.C. } \epsilon$$

compare 23

(38) $\rho = \sum_A \int m_A \delta_D(x - z_A) \frac{ds}{\sqrt{-g}} \Rightarrow$ see L-5 21

$\int f(x) \left(\frac{\delta_D(x-a)}{\sqrt{-g}} \right) d^4x \sqrt{-g} \xrightarrow{\text{MSR}} \int f(a) \delta_D(a-a) d^4x$

correct Def. of Dirac Delta

\Rightarrow for material particles
 Comparing (1) with (23) & get T^{ab} for collection of particles.

(39) $T^{ab} = \rho u^a u^b \rightarrow$ think of it like fluid.
 ρ fluid flowing with u velocity u^a
 Suppose dam is moving along this fluid. what is moment. & Energy in that frame?

$T^{ab} u_b = \rho u^a$
 as $u^b u_b = 1$
 Momentum per Unit Volume
 This is Energy Density
 $\rho u^0 = \text{Energy Density}$
 $\rho u^i = \text{Momentum flux}$

(40) $\rho = T^{ab} \frac{u^a u^b}{-1}$
 This need not be the same velocity as in (39)
 in best frame Both u^a matches
 $\therefore T^{ab}$ is Energy Tensor

ideal fluid (Pressureless & without Density)
 Radiation is ideal fluid

(41) for fluid with $(\rho \neq P)$
 $T^{ab} = (\rho + P) u^a u^b - P g^{ab}$
 $T^a_b = (\rho + P) u^a u_b - P g^a_b$
 $= (\rho + P) u^a u_b - P \delta^a_b$

$$= p u^a u_b - p (g^a_b - u^a u_b)$$

without
Pressure

Projection
Tensor p^a_b

① Sym Tensor

④2 $p_{ab} = p_{ba}$

$$p_{ab} u^a = u_b - u_b = 0$$

∴ Projection Tensor $p_{ab} \perp u^a$

$$\left. \begin{aligned} p_{ab} v^b &= v^{\perp}_a \\ v^{\perp}_a u^a &= 0 \end{aligned} \right\}$$

which is eq. to.

$$\vec{v} - \vec{n} (\vec{v} \cdot \vec{n}) = \vec{v}^{\perp}$$

here \vec{n} is \perp to surface

∴ All the vectors \perp to u^a can be obtained

if u^a, u^b are unit vectors

④3 ∴ $T^a_b = p u^a u_b - p p^a_b$

lines in orthog. space to u^a as $p_{ab} u^a = 0$

if I go in Rest frame of fluid then

$$u^a = (1, 0, 0, 0)$$

∴ p_{ab} is all space

$$T^a_b = p u^a u_b - p p^a_b$$

Pressure acts on space and coeff. of p^a_b is called Pressure

$T^a_b u^b = p u^a$ is known as this

How do I know that T^a_b is symmetric tensor?

(44) $T^a_b u^b = p u^a u_b u^b - p p^a_b u^b = p u^a$
 from (43) $T^a_b u^b = p u^a$ compare with (39)
 Pressure forces / Internal stresses do not contribute to bulk energy flow / momentum. T^a_b is Energy-momentum tensor. Because they cancel out themselves.

(45) $T^a_b = (p + \rho) u^a u_b - p \delta^a_b$
 Trace $T^a_a = (p + \rho) - 4p = \rho - 3p$

For Radiation \equiv ideal fluid $p = \frac{1}{3} \rho$

$\therefore T^a_a = 0$
 This is true for any EM field

(46) Conformal Transform
 $g_{ab} \rightarrow \Omega^2(x) g_{ab} \rightarrow g_{ab} + \epsilon(x) g_{ab}$
 \downarrow
 $1 + \epsilon(x)$
 as $g = \begin{pmatrix} g_{00} & \dots & \dots \\ g_{10} & \dots & \dots \\ \vdots & \dots & \dots \\ g_{30} & \dots & \dots \end{pmatrix}$ lowest order in ϵ
 \rightarrow Diagonalize $\rightarrow \begin{pmatrix} g_{11} \\ g_{22} \\ g_{33} \end{pmatrix}$

(47) EM Action Remains Invariant under Conf. Transform in 8 Dim - Not Conf. Inv.

(48) $A_{EM} = -\frac{1}{16\pi} \int d^4x F_{ab} F^{ab} \sqrt{-g}$
 \downarrow
 $\Omega^4 \sqrt{-g}$
 \downarrow
 $\frac{1}{\Omega^2} g^{ab}$
 \downarrow
 $\frac{1}{\Omega^2} g^{ab}$

(49) $\sqrt{-g} \rightarrow \frac{1}{\Omega^2} g^{ab} \rightarrow$ general $\therefore A_{EM} = A_{EM}$

$F_{ab} \rightarrow \Omega^4 F_{ab}$

Action is Conf. Invariant

Depends on Dimension

⑤0 Proof: $g_{ab} \rightarrow \Omega^2 g_{ab}$

$$g_{ab} = g_{ak} g_{bl} g^{kl} \rightarrow \Omega^2 g_{ak} \Omega^2 g_{bl} g^{kl} \quad (1)$$

$$\Omega^2 g_{ab} = \Omega^2 g_{ak} g_{bl} g^{kl} \quad (2)$$

But (1) & (2) are equal

$\therefore c = \frac{1}{\Omega^2}$

$g_{ab} \rightarrow \frac{1}{\Omega^2} g_{ab}$

Depends on the Dimension

⑤1 Proof: $\sqrt{-g} \rightarrow \Omega^4 \sqrt{-g}$

Assuming g_{ab} is Diagonal Matrix \rightarrow comes 4D

$$g = \begin{vmatrix} g_{ab} & & & \\ & & & \\ & & & \\ & & & \end{vmatrix} = \begin{vmatrix} g_{ab} & & & \\ & 0 & & \\ & & 0 & \\ & & & 0 \end{vmatrix}$$

each $g_{ab} \rightarrow \Omega^2 g_{ab}$

$\therefore g \rightarrow \Omega^8 g$

Non Diag. terms will not contribute.

⑤2 for EM $\sqrt{-g} \rightarrow \Omega^4 \sqrt{-g}$

$A = \int \text{tr}(\phi, \psi, g_{ab}) \sqrt{-g} d^4x$

$\delta A_M = \frac{1}{2} \int \sqrt{-g} d^4x T_{ab} \delta g^{ab}$

If conformally inv. $\therefore \delta A_M = 0 = -\frac{1}{2} \int \sqrt{-g} d^4x T_{ab} \delta g^{ab}$

As $\delta g_{ab} = \epsilon g_{ab}$
 $\delta(g_{ak} g_{bl} g^{kl}) = \epsilon g_{ab}$

$\epsilon g_{ab} + \epsilon g_{ab} + k g_{ab} = \epsilon g_{ab}$

$k = -\epsilon \rightarrow$ Rec. $\delta(g_{ak} g_b^k) = \delta g_{ab}$

$\therefore \delta g^{ab} = -\epsilon g^{ab}$

$(\delta g_{ak}) g_b^k + (g_{ak}) \delta g_b^k = \delta g_{ab}$

$\delta A_M = -\frac{1}{2} \int \sqrt{-g} d^4x T^{ab} g_{ab} \quad \epsilon(x) = 0 \quad \forall \epsilon$

$\therefore T^a_a = 0$

\therefore for any Action which is (or formally) Invariant $T^a_a = 0$

55) EM in 8 Dim.

$\sqrt{-g} \rightarrow \Omega^8 \sqrt{-g}$

\therefore in 8 Dim. Action will not be conforme inv.

$\therefore T^a_a$ in 8 Dim will not vary.

6) $A = \frac{1}{16\pi} \int F_{ab} F_{em} g^{ae} g^{bm} \sqrt{-g} d^4x \rightarrow$ inv.
 $= \frac{1}{16\pi} \int F_{ab} F_{em} g_{ae} g_{bm} \sqrt{-g} d^4x \rightarrow$ if done in lower index Not inv.
 $\downarrow \quad \downarrow \quad \downarrow$
 $\Omega^2 \quad \Omega^2 \quad \Omega^4 \sqrt{-g} \rightarrow \Omega^8 \rightarrow$ inv.

2-form ?

① T_{ab} for Material Particles

$$T_{ab} = \rho u^a u^b = \text{Energy Mom. Tensor.}$$

$$T_{ab} u^b = \rho u^a = \text{Momentum Density}$$

② T_{ab} for EM field.

Anything except gravity is matter.

$$A_m = -\frac{1}{16\pi} \int d^4x \sqrt{-g} g^{ak} g^{bj} F_{kj} F_{ab}$$

$$\delta A_m = -\frac{1}{16\pi} \int d^4x F_{kj} F_{ab} \left[\begin{aligned} &\sqrt{-g} (\delta g^{ak}) g^{bj} \\ &+ \sqrt{-g} (\delta g^{bj}) g^{ak} \\ &+ (\delta \sqrt{-g}) g^{ak} g^{bj} \end{aligned} \right]$$

w.r.t. g_{ab}

in SR varied w.r.t. A_j

$$= -\frac{1}{16\pi} \int d^4x F_{kj} F_{ab} \left[2 \sqrt{-g} \delta g^{ak} g^{bj} \right]$$

$$\left[\frac{\delta g^{ak} g^{bj}}{2 \sqrt{-g}} \delta g \right]$$

$$\approx -\frac{1}{16\pi} \int d^4x F_{kj} F_{ab} \left[2 \sqrt{-g} \delta g^{ak} g^{bj} - \frac{(\delta g^{ak} g^{bj}) g_{mn} \delta g^{mn}}{2 \sqrt{-g}} \right]$$

$$= \frac{-1}{16\pi} \int d^4x F_{kj} F_{ab} \left[2\sqrt{-g} g^{ak} g^{bj} - \frac{g^{ak} g^{bj} g_{mn} g^{mn}}{2} \right] \quad 72$$

$$\boxed{J_{ab} = \sqrt{-a} \sqrt{-b}} \quad ?$$

$$S_{EM} = \frac{-1}{16\pi} \int \sqrt{-g} \left[2 F_k^b F_{ab} g^{ak} - \frac{(F_{ab} F_{ab}) g_{mn} g^{mn}}{2} \right] d^4x$$

let $F^{ab} F_{ab} = F^2$

$$= \frac{-1}{16\pi} \int \sqrt{-g} \left[2 F_k^b F_{ab} g^{ak} - \frac{F^2 g_{ak} g^{ak}}{2} \right] d^4x$$

$$= \frac{-1}{16\pi} \int \sqrt{-g} g^{ak} d^4x \left[F_k^b F_{ab} - \frac{F^2 g_{ak}}{8} \right]$$

$$\boxed{S_{EM} = \frac{1}{2} \int d^4x \sqrt{-g} g^{ab} T_{ab}}$$

$$3) T_{ak} = -\frac{1}{4\pi} \left[F_k^b F_{ab} - \frac{F^2 g_{ak}}{4} \right]$$

$$T_{ak} = -\frac{1}{4\pi} \left[F_k^b F_{ab} - \frac{F^2 g_{ak}}{4} \right] \xrightarrow{\text{sign}}$$

$$= \frac{1}{4\pi} \left[F^{kb} F_{ba} + \frac{F^2 g_{ka}}{4} \right]$$

$$4) T_a^a = \frac{1}{4\pi} \left[F^{ab} F_{ba} + \frac{F^{ab} F_{ab} \cdot 4}{4} \right]$$

$$= \frac{1}{4\pi} \left[F_a^a F_{ba} - F^{ab} F_{ba} \right]$$

= 0 as EM Action is Conf. Invariant

(5) Varying Action w.r.t. g_{ab} we get T_{ab}
 Varying Action w.r.t. A_i we get Maxwell Eqn

Vary. Action w.r.t. A_i we get Maxwell Eqn in curved spacetime.

Can we get T_{ab} from Action in SR?

→ There is a procedure to get T_{ab} but there are 2 problems in this
 1) T_{ab} not sym
 2) there is a procedure to make it sym but it is not unique
 Th. T_{ab} not sym
 Angular mom. not conserved

(6) $T^k_a = \frac{1}{4\pi} [F^{kb} F_{ba} + \frac{F^2}{4} \delta^k_a]$

Also valid in SR just $g_{ab} \rightarrow \eta_{ab}$.

∴ in SR there is no unique def. T_{ab}
 Extra features had to be brought to do that
 But in GR assumed minimal coupling there is unique.
 Why T^k_a is the Energy-Momentum Tensor?

(7) $T^0_0 = \frac{1}{4\pi} [F^{0\alpha} F_{\alpha 0} + \frac{2(B^2 - E^2)}{4}]$

$= \frac{1}{4\pi} [E^2 + \frac{B^2 - E^2}{2}]$ → EM Energy Density

$= \frac{1}{8\pi} [E^2 + B^2] = \text{Energy Density in SR}$

energy density \downarrow true

(8) $T^\alpha_0 = \frac{1}{4\pi} [F^{\alpha b} F_{b0}] = \frac{1}{4\pi} [F^{\alpha\beta} F_{\beta 0}]$

$T^{0\alpha} = \frac{1}{4\pi} (\vec{E} \times \vec{B})^\alpha = \text{EM Momentum Density}$ work out

∴ T^k_a which is the energy Momentum Tensor of EM field act as a source of Grav. field.

9) $T_{\alpha\beta}$ do not have direct interpretation in EM.

But in plasma, they can be thought of as some stresses in magnetic field.

How?

10) T_{ik} is the source of gravity? → EM field produce grav. field around it.



Box went on a curved line light should attract grav. field. ←

By principle of Eq. in presence of gravity

∴ Grav. field should attract light

11) Scalar field

Ascalar $\stackrel{SR}{=} \int d^4x \left(\frac{1}{2} (\partial_a \phi \partial^a \phi) - V(\phi) \right)$

$\stackrel{GR}{=} \int d^4x \sqrt{g} \left[\frac{1}{2} (\partial_a \phi \partial_b \phi g^{ab}) - V(\phi) \right]$

$\delta A_S = \int d^4x \left[L \left(-\frac{1}{2} g_{ik} \delta g^{ik} \sqrt{g} \right) + \sqrt{g} \frac{\delta L}{\delta g^{ab}} \delta g^{ab} \right]$

w.r.t. g_{ab} $= \int d^4x \left[-\frac{L}{2} g_{ik} \delta g^{ik} \sqrt{g} + \sqrt{g} \frac{1}{2} \partial_i \phi \partial_k \phi \delta g^{ik} \right]$

$= \int d^4x \frac{\delta g^{ik}}{2} \sqrt{g} \left[-L g_{ik} + \partial_i \phi \partial_k \phi \right]$

$\delta A_S = \int \frac{1}{2} d^4x \sqrt{g} T_{ik} \delta g^{ik} \quad \therefore T_{ik} = -L g_{ik} + \partial_i \phi \partial_k \phi$

(12) $T^i_k = \partial^i \phi \partial_k \phi - L \delta^i_k$

$H = \dot{\phi} \dot{q} - L$
 Earlier we made T^i_k from this.

(13) $T^0_0 = \dot{\phi}^2 - \left(\frac{\dot{\phi}^2}{2} - \frac{|\nabla\phi|^2}{2} - V \right)$
 $= \frac{1}{2} (\dot{\phi}^2 + |\nabla\phi|^2) + V \equiv H = \frac{\dot{q}^2}{2} + V$

for some suitable V , $T^0_0 > 0$ → why?

(14) $L \rightarrow L + k \rightarrow \text{const.} \rightarrow$ EOM remains invariant

$T^a_b \rightarrow T^a_b + k \delta^a_b$ from (12)

Energy Mom. Tensor contributed by constant added to Lag.

(5) This concept doesn't \exists in SR.
 coz. adding const. in SR, EOM remains same.

How to know this $k \delta^a_b$ is Energy Mom. Tensor.
 No kinetic energy term.

(6) let $L = V + k$
 \uparrow
 const

A scalar \rightarrow

A scalar $\uparrow \int d^4x \sqrt{-g} k$

$\sqrt{-g}$ coupled to constant

(7) $T^a_b = k \delta^a_b = \text{diag}(k, k, k, k)$
 $= \begin{pmatrix} k & & & \\ & k & & \\ & & k & \\ & & & k \end{pmatrix}$

Similar happens in T^a_b symmetric Tensor, & Dist. function.

(18) $T^a_b = (p + \rho) u^a u_b - p \delta^a_b$ (ideal fluid)
 in rest frame.

$u^a = (1, 0, 0, 0)$

ans $T^a_b = (p + \rho) u^a u_b - p \delta^a_b = (p, -p, -p, -p)$

(19) \therefore (17) is eq to (18) with $p = -k$

(20) Dark Energy behaves as if it have -ve pressure. which is what is happening here.

(21) As T^a_b has to be +ve. $\therefore k$ +ve in (17)
 But then p pressure is -ve.

Rec. while δx^A we assume t_0 is fixed & we know the exterior field

(22) when you just add const. to matter lag. Gravity picks up the term which behaves like fluid with -ve pressure

Matter EOM remains invariant i.e. $\delta x^A = 0$

Why? $\rho = 0$

(23) Gravity fixes the zero point of the energy. ρ & added constant Matter EOM remains inv. \rightarrow why? $\int k \sqrt{-g} d^4x \neq 0$

By looking at matter I can't tell if const. has been added. But by looking at grav. field I can know if that const. is there or not.

$k=0$ is valid. \therefore This energy momentum tensor of vacuum. if QFT field is L.I. then vacuum fluctuation $T^a_b = k \delta^a_b$

(24) $T^a_b = k \delta^a_b$ is the most general Lorentz invariant Energy Momentum tensor. As T^a_b is 2nd Rank & Sym. \therefore Only available option is δ^a_b

$\therefore T^a_b = k \delta^a_b$ k has to be constant so as T^a_b is L.I.

Ordinary Derivative \uparrow Covariant Derivative of metric = 0

(25) $A_{tot} = A_m(\phi_A, g) + A_g$

$A_g = \int d^4x \sqrt{g} \mathcal{L}_{grav}(g_{ab}, \partial_c g_{ab})$

(26) Varying w.r.t. g_{ab} A_m would give T_{ab}
 A_{field} would give sth.
 This method works for everything except gravity.

(27) For field Eqn to be covariant we want our Action to be generally covariant.
 But the converse is not true.
 i.e. if the field eqn has to be covariant it is not necessary Action has to be generally covariant.

(28) If in Action non covariant part comes as in Total Divergence then field eqn can be generally covariant. non cov. \therefore covariant field eqn can be obtained from Action

(29) But most generally, Action should be gen. cov

$\mathcal{L}_{grav}(g_{ab}, \partial_c g_{ab})$ can't be a scalar

Let $\mathcal{L}_{grav}(g_{ab}, \partial_c g_{ab}) = \partial_i g_{ab} \partial_j g_{cd} g^{ij} g^{ab} g^{cd} + g^{ab} g_{ab}$

Then going to L.I.f.

$g_{ab} = \eta_{ab}$
 $\partial_i g_{ab} = 0$ } \therefore All scalars we would get is trivial. \exists const.

(30) So $\mathcal{L}_{grav}(g_{ab}, \partial_c g_{ab}, \partial_i \partial_j g_{ab}) \equiv \mathcal{L}(g, \dot{g}, \ddot{g})$

$$\begin{aligned}
 \textcircled{31} \quad \delta A &= \int dt \delta L(q, \dot{q}, \ddot{q}) \\
 &= \int dt \left(\frac{\partial L}{\partial q} \delta q + \frac{\partial L}{\partial \dot{q}} \delta \dot{q} + \frac{\partial L}{\partial \ddot{q}} \delta \ddot{q} \right) \\
 &= \int dt \left(\frac{\partial L}{\partial q} \delta q + \left(\frac{\partial L}{\partial \dot{q}} - \frac{d}{dt} \left(\frac{\partial L}{\partial \ddot{q}} \right) \right) \delta \dot{q} \right) + \int dt \frac{d}{dt} \left(\frac{\partial L}{\partial \ddot{q}} \delta \ddot{q} \right) \\
 &= \int dt \left(\frac{\partial L}{\partial q} - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} - \frac{d}{dt} \left(\frac{\partial L}{\partial \ddot{q}} \right) \right) \right) \delta q \\
 &\quad + \int dt \frac{d}{dt} \left(\left(\frac{\partial L}{\partial \dot{q}} - \frac{d}{dt} \left(\frac{\partial L}{\partial \ddot{q}} \right) \right) \delta \dot{q} \right) + \int dt \frac{d}{dt} \left(\frac{\partial L}{\partial \ddot{q}} \delta \ddot{q} \right)
 \end{aligned}$$

EOM ←

If $\delta A = \int dt \delta L(q, \dot{q})$

$$\delta A = \int dt \left(\frac{\partial L}{\partial q} - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} \right) \right) \delta q + \int dt \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} \delta q \right)$$

↓
 Only v, q at initial position is req. to evolve the EOM

$$\textcircled{32} \quad \left(\frac{\partial L}{\partial \dot{q}} - \frac{d}{dt} \left(\frac{\partial L}{\partial \ddot{q}} \right) \right) \delta q \Big|_{t=t_1}^{t=t_2} = 0$$

$$\left(\frac{\partial L}{\partial \ddot{q}} \delta \ddot{q} \right) \Big|_{t=t_1}^{t=t_2} = 0$$

$$\textcircled{33} \quad \text{EOM: } \frac{\partial L}{\partial q} - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} - \frac{d}{dt} \left(\frac{\partial L}{\partial \ddot{q}} \right) \right) = 0$$

3rd Order
 In Newton limit 3rd order has to vanish
 But how? ∴ 2nd Order EOM should be the

(34) 2nd order EOM can be obtained in $L_{\text{grav}}(g_{ab}, \partial_c g_{ab}) \partial_i \partial_j g_{ab}$ case only when $\partial_i \partial_j g_{ab}$ is linear in L_{grav} .

(35) Let $L_{\text{grav}} = L_1(g_{ab}, \partial_c g_{ab}) + \frac{1}{\sqrt{-g}} \partial_k \left(\sqrt{-g} \delta^k(\dots) \right)$

↑
2nd order
↓
will vanish.
∴ we don't have to vary this

But earlier what we used to do: we vary first & then $\partial_k(\dots)$ comes like $\int dt \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} \delta \dot{q} \right)$ which we vanish by assuming q at end pts fixed.

(36) ∴ Now will vary L_1 only & get 2nd order EOM

(37) $L_1 = L + \frac{d}{dt} f(q, t)$

$$\int_{t_1}^{t_2} L_1 dt = \int L dt + \int dt \frac{d}{dt} f(q, t)$$

$$= \int L dt + \int df(q, t)$$

$$\int L_1 dt = \int L dt + f(q_2, t_2) - f(q_1, t_1)$$

we have assumed q to be fixed at end pts.

$$\therefore \delta \int L_1 dt = \delta \int L dt \Rightarrow \delta A_1 = \delta A$$

(38) $L_1 = L + \frac{d}{dt} f(q, \dot{q}, t)$

$S_1 = S + \int d f(q, \dot{q}, t)$

only q is fixed at End pts

If both \dot{q} , q are held fix at end pts then f will not contribute

$\delta S_1 = \delta S + \delta f(q_2, \dot{q}_2, t) - \delta f(q_1, \dot{q}_1, t)$
 Here we are integrating over a 2 Hyper surface

(39) $\int \sqrt{g} g_{\alpha\beta} d^4x = \int L_1 \sqrt{g} d^4x + \int \partial_\mu (\sqrt{g} Q^\mu(g, \partial_j g^{ab})) d^4x$

If g fix field on Hyper Surfaces then derivative of those fields also get fixed

$\int \sqrt{g} Q^\mu(g, \partial_j g^{ab}) d^3x$

Derivatives normal to it are not fixed

There are some terms which cannot be integrated away.

(40) \therefore Now lets choose ~~g_{ab}~~ which can vanish
 $R^i_{jkl} \Rightarrow R_{je} = g^k_i R^i_{jkl} = \delta^k_i R^i_{jkl} = R^i_{jil}$

Linear in 1st Deriv. Γ
 $R = g^{ab} R_{ab}$

\therefore Linear in 2nd Deriv. Γ
 $\therefore R$ is linear in 2nd Der. Γ

~~$\int \sqrt{g} \partial_\mu (\sqrt{g} Q^\mu(g, \partial_j g^{ab})) d^4x$~~

(41) As we have varied A_j to get field E_i
 Here vary w.r.t g_{ab} .

(42) $A_g = \frac{-1}{16\pi k} \int R \sqrt{-g} d^4x$

$\delta(R \sqrt{-g}) = \delta(\sqrt{-g} g^{ab} R_{ab})$ $R = g^{ij} R_{ij}$
 $= \frac{-1}{2} \sqrt{-g} g_{ab} \delta g^{ab} R + \sqrt{-g} \delta g^{ab} R_{ab}$
 $+ \sqrt{-g} g^{ab} \delta R_{ab}$

$G_{ab} = \sqrt{-g} \delta g^{ab} \left[R_{ab} - \frac{g_{ab} R}{2} \right] + \sqrt{-g} g^{ab} \delta R_{ab}$

(43) $g^{ab} \delta R_{ab} \sqrt{-g} = \sqrt{-g} g^{ab} \delta(R^i_{aib})$
 as this is the tensor divergence
 \therefore I can compute it in any frame.

\therefore u.l.f. $\Rightarrow R^a_{bcd} = \partial^a \Gamma^c_{bd} - \partial^c \Gamma^a_{bd} + \Gamma^a_{\Gamma} - \Gamma^c_{\Gamma}$
 $\delta R^a_{bcd} = \delta(\partial^a \Gamma^c_{bd}) - \delta(\partial^c \Gamma^a_{bd}) + \Gamma \delta \Gamma - \Gamma \delta \Gamma$

u.l.f. Γ vanish
 $\therefore = \sqrt{-g} g^{ab} \delta(\partial_i \Gamma^i_{ab} - \partial_b \Gamma^i_{ai})$
 $= \sqrt{-g} g^{ab} (\partial_i (\delta \Gamma^i_{ab}) - \partial_b (\delta \Gamma^i_{ai}))$

$$= \left\{ \partial_k \right\} \sqrt{g} (g^{ab} \delta \Gamma_{ab}^k - g^{ak} \delta \Gamma_{ai}^i)$$

$$= 2 \partial_c \left(\sqrt{g} g^{bk} \delta \Gamma_{bd}^a \right)$$

(44) Γ_{bc}^a are not tensors
Th. But $\delta \Gamma_{bc}^a$ are tensors } Scalar \therefore valid in all frames

in \parallel Transport

$$\frac{dv^i}{d\lambda} = - \Gamma_{kl}^i \frac{dx^k}{d\lambda} v^l \quad \text{--- (1)}$$

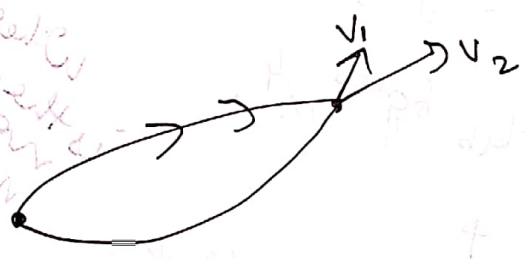
If $g_{ab} \rightarrow g_{ab} + \delta g_{ab}$
 then Γ also changes
 But all other things remain same in (1)

$$\therefore \delta v_{||}^i = - \delta \Gamma_{kl}^i x^k v^l$$

See Emil's Definition of \parallel Transport

i.e. $\frac{dv_{||}^i}{d\lambda} = - \Gamma_{kl}^i \frac{dx^k}{d\lambda} v^l$

$$\frac{dv_{||}^i}{d\lambda} = - (\Gamma_{kl}^i + \delta \Gamma_{kl}^i) \frac{dx^k}{d\lambda} v^l$$



v_1 = Taking vector when g_{ab} is there
 v_2 = Taking vector when $g_{ab} + \delta g_{ab}$ is there

Diff. B/w 2 vectors at same pt. Now taking the diff.

\therefore Vector $\leftarrow \delta v_{||}^i = - \delta \Gamma_{kl}^i x^k v^l$ \rightarrow vector

$\therefore \delta \Gamma$ is tensor

(41) A:

(45) Transf. of Γ'

$$\Gamma' = \Gamma L L L + L \delta^2 L$$

This is quad. of Γ
 \therefore in $\delta \Gamma'$
this cancels out

(42)

\therefore Transf. of $\delta \Gamma'$ is Tensorial.

Scalar \therefore valid in all frames

(46) from (43)

$$g^{ab} \delta R_{ab} \sqrt{g} = \partial_k \left\{ \sqrt{g} (g^{ab} \delta \Gamma_{ab}^k - g^{ak} \delta \Gamma_{ai}^i) \right\}$$

$$\text{Let } \delta v^k \equiv (g^{ab} \delta \Gamma_{ab}^k - g^{ak} \delta \Gamma_{ai}^i)$$

vector $\therefore \delta v^k$ is vector

$$\therefore \nabla_k (\delta v^k) = \frac{\partial_k (\sqrt{g} \delta v^k)}{\sqrt{g}}$$

$$\therefore g^{ab} \delta R_{ab} \sqrt{g} = \sqrt{g} \nabla_k (\delta v^k)$$

(47)

$$(-16\pi k) \delta A_g = \int d^4x \delta (\sqrt{g} R)$$

$$= \int \sqrt{g} g_{ab} \delta g^{ab} d^4x$$

$$+ \int \sqrt{g} d^4x \nabla_k (\delta v^k)$$

$$= \int \sqrt{g} g_{ab} \delta g^{ab} d^4x$$

$$\int \sqrt{|h|}^{1/2} d^3x n_x (\delta v^x)$$

where n_x is the unit normal $n_x = \frac{\partial x}{\partial x^4}$ where x^4 is the time coordinate

18

$$\textcircled{48} \delta v^k = g^{ab} \delta \Gamma_{ab}^k - g^{ak} \delta \Gamma_{ai}^i$$

$$\delta \Gamma_{ab}^k = \delta \left(\frac{g^{kc}}{2} (-\partial_c g_{ab} + \partial_a g_{bc} + \partial_b g_{ca}) \right)$$

Assuming $\delta g^{ab} = 0$

$$\delta \Gamma_{ab}^k = \frac{g^{kc}}{2} (-\delta \partial_c g_{ab} + \delta \partial_a g_{bc} + \delta \partial_b g_{ca})$$

$$\delta \Gamma_{ai}^i = \frac{g^{ik} \delta \partial_a g_{ik}}{2}$$

$$\textcircled{49} \delta v^k = g^{ab} \frac{g^{kc}}{2} (-\delta \partial_c g_{ab} + \delta \partial_a g_{bc} + \delta \partial_b g_{ca})$$

$$- \frac{g^{ab} g^{ik}}{2} \delta \partial_a g_{ik}$$

$$= \frac{g^{ak} g^{cb}}{2} (-\delta \partial_a g_{cb} + \delta \partial_c g_{ba} + \delta \partial_b g_{ac}) - \frac{g^{ak} g^{cb}}{2} (\partial_a g_{cb})$$

$$= \frac{g^{ak} g^{cb}}{2} (-2 \delta \partial_a g_{cb} + 2 \delta \partial_c g_{ba})$$

$$= g^{ak} g^{cb} (\delta \partial_c g_{ba} - \delta \partial_a g_{cb})$$

$$\textcircled{50} \eta_k \delta v^k = \eta^a g^{cb} (\delta \partial_c g_{ba} - \delta \partial_a g_{cb})$$

$$\textcircled{51} h_{\alpha\beta} = g_{ab} e_\alpha^a e_\beta^b$$

where $e_\alpha^a = \frac{\partial x^a}{\partial y^\alpha}$

$$ds^2 = g_{ab} dx^a dx^b$$

$$= g_{ab} \frac{\partial x^a}{\partial y^\alpha} \frac{\partial x^b}{\partial y^\beta} dy^\alpha dy^\beta = h_{\alpha\beta} dy^\alpha dy^\beta$$

$\beta, \alpha = 1, 2, 3$

$b, a = 0, 1, 2, 3$

(52) As n_a is the normal

(41)

$$\therefore n_a e^a_\alpha = 0$$

Till this for any $\Gamma/S/N$ geodesic

$$(53) \therefore h_{\alpha\beta} = g_{ab} e^a_\alpha e^b_\beta = (g_{ab} + \epsilon n_a n_b) e^a_\alpha e^b_\beta$$

(42)

$$h_{\alpha\beta} = h_{ab} e^a_\alpha e^b_\beta$$

(54) Inverse of it

$$h^{ab} = h^{\alpha\beta} e^a_\alpha e^b_\beta$$

$$h^{ab} = g^{ab} + \epsilon n^a n^b$$

$$(55) \eta_k \delta v^k = n^a g^{cb} (\delta \partial_c g_{ba} - \delta \partial_a g_{cb})$$

$$= n^a (h^{cb} - \epsilon n^c n^b) (\delta \partial_c g_{ba} - \delta \partial_a g_{cb})$$

Anti in c & a

$$= n^a h^{cb} (\delta \partial_c g_{ba} - \delta \partial_a g_{cb})$$

$$- \epsilon \frac{n^a n^c n^b}{\text{Sym c \& a}} (\delta \partial_c g_{ba} - \delta \partial_a g_{cb})$$

Anti in c & a

$$= n^a h^{cb} (\delta \partial_c g_{ba} - \delta \partial_a g_{cb})$$

(56) If $\delta g_{ab} \Big|_{\partial \Sigma} = 0 \Rightarrow$

$(\delta \partial_c g_{ab}) e^c_\alpha = 0$
Tangential Derivatives also get fixed.

(57) But from (54)

$$h^{cb} = h^{\alpha\beta} e^c_\alpha e^b_\beta$$

Putting in (55)

$$\eta_k \delta v^k = n^a h^{\alpha\beta} e^c_\alpha e^b_\beta (\delta \partial_c g_{ba} - \delta \partial_a g_{cb})$$

$$= -n^a h^{cb} \delta \partial_a$$

58) $A = \frac{-1}{16\pi k} \left(\int \sqrt{-g} d^4x G_{ik} g^{ik} - \int_{\partial V} \underbrace{n^a e_b^c \delta g_{ab} \sqrt{h} dy^3}_{\text{Normal Derivative term}} \right)$

59) $S_{GHY} = \frac{-1}{8\pi k} \int_{\partial V} d^3y \sqrt{h} k$ $n^a \delta_a$

$K_{ab} = \nabla_a n_b e^a_\alpha e^\beta_b$
 k : Trace of Extrinsic Curvature.

K_{ab} is comp. of Tang. $\nabla_a n_b$ & Normal comp. of $\nabla_\beta A^\alpha e^\beta_b$

60) As $\delta g_{ab}|_{\partial V} = 0$

& $h_{\alpha\beta} = g_{ab} e^a_\alpha e^b_\beta$

$\therefore \delta h_{\alpha\beta}|_{\partial V} = \delta g_{ab}|_{\partial V} e^a_\alpha e^b_\beta = 0$

$\Rightarrow \delta h_{\alpha\beta}|_{\partial V} = 0$ Induced metric gets fixed

61) As the induced metric is fixed on ∂V , \therefore only h fixed $\delta h = 0$
 qty to be varied is k

62) $k = \nabla_a n^a$ $= g_{ab} \nabla^b n^a = (h_{ab} - \epsilon n_a n_b) \nabla^b n^a$

$$K_{ab} = \nabla_\beta n_\alpha e^a_\alpha e^\beta_b$$

$$= h_{ab} e^\alpha_\alpha e^\beta_\beta n^\alpha n^\beta$$

$$= K^\beta_\alpha (g_{ab} n^\alpha n^\beta)$$

$$= K^\beta_\alpha \nabla_\beta n^\alpha$$

But $\nabla_a (n^a n_b) = 0$
 $\Rightarrow n_b \nabla_a n^b = 0$

$\therefore k = h_{ab} \nabla^b n^a = g_{ad} g^{bc} h^{cd} \nabla_b n^a = h^{ab} \nabla_b n^a$

$$(3) K = h^{ab} (\partial_b n_a - \Gamma_{ba}^i n_i)$$

$$\delta K = \delta h^{ab} (\partial_b n_a - \Gamma_{ba}^i n_i) + h^{ab} (\delta \partial_b n_a - \delta \Gamma_{ba}^i n_i)$$

Induced metric ϵ gets fixed along $\partial \Sigma$

$$= h^{ab} (\delta \partial_b n_a - \delta \Gamma_{ba}^i n_i) - h^{ab} \Gamma_{ba}^i \delta n_i$$

$$n_a = \frac{\epsilon \partial_a \phi}{|\partial_\alpha \phi \partial^\alpha \phi|^{1/2}} = \frac{\epsilon \partial_a \phi}{|\partial_\alpha \phi \partial_\beta \phi g^{\alpha\beta}|^{1/2}}$$

Involves metric

When varying our boundaries are fixed

$$\delta \phi = 0$$

& as also we have fixed $\delta g_{\alpha\beta}|_{\partial \Sigma} = 0$ our boundary

Compare with Paddy's note $\delta n_a = 0$ though it involves metric

$n_i = A(x) \partial_i \phi$
 $\delta n_i = n_i \delta(\ln A)$

$$\delta \partial_\beta n_a = 0$$

$$\begin{aligned} \therefore \delta K &= -h^{\alpha\beta} \delta \Gamma_{\alpha\beta}^{\mu} n_\mu = -\frac{h^{\alpha\beta}}{2} g^{\mu\nu} (\delta g_{\alpha\mu, \beta} + \delta g_{\beta\mu, \alpha} - \delta g_{\alpha\beta, \mu}) n_\nu \\ &= \frac{h^{\alpha\beta}}{2} \delta g_{\alpha\beta, \mu} n^\mu \end{aligned}$$

$$1) \int_{\partial \Sigma} \epsilon K |h|^{1/2} d^3 y = \int_{\partial \Sigma} \epsilon \delta K |h|^{1/2} d^3 y$$

- 1) How the gravity modifies spacetime?
- 2) $ds^2 = g_{\alpha\beta} dx^\alpha dx^\beta$
- 3) How to know if the spacetime is curved/flat?
- 4) Proof that arbitrary $g_{\alpha\beta}$ can't be converted to $\eta_{\alpha\beta}$.
- 5) Proof that we can always transform to L.I.F?
- 6) Defn of vector (Abstract & Transformation law)?
- 7) Defn of Dual vector (Abstract & Transformation law)?

If metric is defined; both defn become equal.

- 8) Defn of forms.
- 9) Defn of Tensor.
- 10) Multiplication/Addition/Subtraction/Contraction of 2 tensors not defined on manifold?

Integration of vectors/tensors not defined?

$\int \omega_i A^i dx$ X Not defined. } Any index left in
 $\int A_i dx$ X Not defined } under \int is not defined.

Definition $DA^\alpha, \nabla_\beta A^\alpha \rightarrow$ In terms of Gauge theory

Relation of them with straight line $\frac{DU^\alpha}{d\lambda} = 0$
 $\frac{dU^\alpha}{d\lambda} + \Gamma^\alpha_{\beta\gamma} U^\beta \frac{dx^\gamma}{d\lambda} = 0$
 $\frac{dV^k}{d\lambda} = \frac{DU^k}{d\lambda} e_k \rightarrow \frac{dV^k}{d\lambda} = \partial_j V^i v^j e_i + V^i v^j \partial_j e_i$
 $\frac{dV^k}{d\lambda} + \Gamma^k_{ij} V^i v^j = 0$
 $\frac{dV^k}{d\lambda} + \Gamma^k_{ij} V^i v^j = 0$
 Definition of // Transport? $\Gamma V \rightarrow$ Matrix multpn

Order DE \rightarrow Always solvable

Transformation law for Γ
 $\rightarrow d$ for scalar fn; D follows product rule
 To prove if D follows prod rule $\Leftrightarrow \nabla$ follows prod. rule.

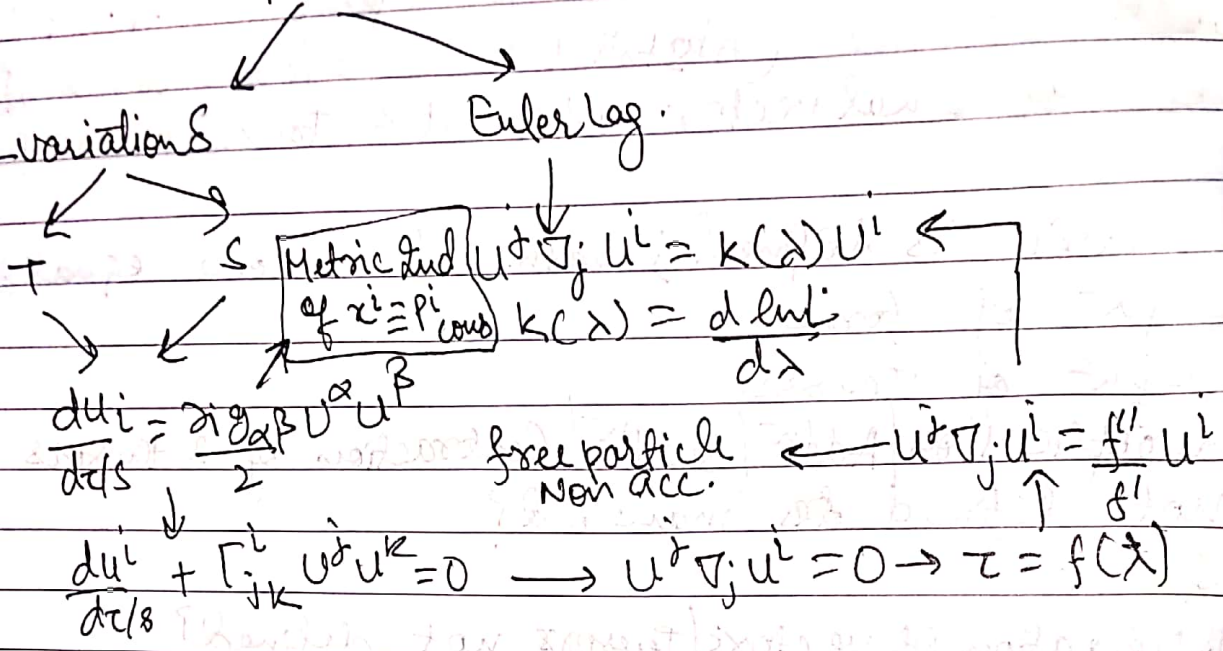
∇ duals & ∇ Tensors? $\rightarrow \nabla_i g_{\alpha\beta} = 0$

(14) Demanding Γ is sym $\Rightarrow \Gamma$ in terms of $g_{\alpha\beta}$

(15) $dl = \sqrt{\pm g_{\alpha\beta} dx^\alpha dx^\beta}$ depending on T/S.
 $dl^2 = dz^2$ or ds^2 depending on T/S.

$dA = -m dl$

(16) $dl = \sqrt{\pm g_{\alpha\beta} dx^\alpha dx^\beta}$



Extremizes means max. proper time for time like Geod.
 max. proper distance for spacelike Geod.

Specifically,

This is max. for short separation

& for larger separation this becomes a saddle point

⇒ In CM, this is minimum for shorter separation
 & for larger separation this becomes saddle point

(17) What is the weak field limit of EDM for particle?

(18) What are the uses of Affine parameter?

- FRW for non null cases easy to solve
- FRW for null cases

(19) Why For affinely parameterized Geod. if the Geod. is T/S/N then it remains so?

(20) $L = \sqrt{g_{ij} dx^i dx^j}$
 $L_2 = \sqrt{g_{ij} u^i u^j}$ } Both gives same EDM

- ② lead eqn (1) Extremizes length $\Rightarrow \therefore$ Req. metric
 (2) Tangent vectors $\parallel \Rightarrow \therefore$ Req. Γ

② What are the all formulas of g

\swarrow Divergence \searrow $\partial_i g$

③ Why all local things should match in GR & SR eg. U^i, n_i ?

④ EM in Curved spacetime

$$F_{ik} = \nabla_i A_k - \nabla_k A_i$$

$$\nabla_i F^{ik} = 4\pi J^k = \frac{\partial_j (\sqrt{g} F^{jk})}{\sqrt{g}}$$

in SR $\partial_i F^{ik} = 4\pi J^k \Rightarrow \partial_k \partial_i F^{ik} = \partial_k J^k = 0$

$$\int d^4x \partial_k J^k = \int d^3x J^0 = \text{const}$$

in GR

$$\partial_k \frac{\partial_i (\sqrt{g} F^{ik})}{\sqrt{g}} = 0 = \frac{\partial_k (\sqrt{g} J^k)}{\sqrt{g}} = \nabla_k J^k$$

$$\int \nabla_k J^k d^4x \sqrt{g} = \int |h|^{1/2} J^0 d^3x = \text{const.}$$

⑤ Lie Transport requires Γ to be defined. Lie transport requires vector field to be defined in the spacetime.

⑥ 2 ways to define Lie Transf $= \mathcal{L}_\xi v = \ell t \frac{v_Q - v_P}{d\lambda}$

$$\delta A^i = A^i(Q) - A^i(P)$$

$$\mathcal{L}_\xi v = \ell t \frac{v_Q - v_P}{d\lambda}$$

$$\textcircled{27} \quad \begin{aligned} \alpha_t V^i &= t^\alpha \partial_\alpha V^i - V^\alpha \partial_\alpha t^i \\ &= t^\alpha \nabla_\alpha V^i - V^\alpha \nabla_\alpha t^i \\ &= \text{Tensor qty.} \end{aligned}$$

$$\alpha_t V^i = -\alpha_j t^i$$

$\textcircled{28}$ Similarly 2 ways to define $\alpha_t g^{ij}$, $\alpha_t A_i$

$$\textcircled{1} \quad \alpha_t g^{ij} = \frac{g^{ij}(Q) - g^{ij}(P)}{dx}$$

$$\textcircled{2} \quad \alpha_t g^{ij} = \frac{g^{ij}(Q) - g^{ij}(P)}{dx}$$

$$\textcircled{29} \quad \begin{aligned} \alpha_t A^{ij} &= t^\alpha \partial_\alpha A^{ij} - A^{\alpha j} \partial_\alpha t^i - A^{i\alpha} \partial_\alpha t^j \\ &= t^\alpha \nabla_\alpha A^{ij} - A^{\alpha j} \nabla_\alpha t^i - A^{i\alpha} \nabla_\alpha t^j \end{aligned}$$

$$\alpha_t A_i = t^\alpha \partial_\alpha A_i + A_\alpha \nabla_i t^\alpha$$

we conclude the α follows product rule.

$$\textcircled{30} \quad \text{Def. } \alpha_t f = t^\alpha \partial_\alpha f \equiv \frac{df}{dx}$$

$$\textcircled{31} \quad \alpha_t g_{ij} = \nabla_i t_j + \nabla_j t_i$$

$$\alpha_t g^{ij} = -(\nabla^i t^j + \nabla^j t^i)$$

$\textcircled{32}$ Def. of spacetime symmetric \equiv Network of Distances

$$\alpha_k g_{ij} = 0 \quad k \text{ vector field} \equiv \text{killing field}$$

$$\textcircled{33} \quad \text{if } k \in \text{Basis vectors} \Rightarrow \frac{\partial g_{ij}}{\partial x^i} = 0$$

if $\frac{\partial g_{ij}}{\partial x^i} = 0 \Rightarrow k \neq \frac{\partial}{\partial x^i}$ $\alpha_k g_{ij} = 0$ in general as if tensor is 0 in one frame it remains zero in all other frames

if $k \in$ killing vector then coord. syst. can be const. s.t. k is basis vector in that coord syst & $\therefore \frac{\partial g_{ij}}{\partial x^i} = 0$

$\textcircled{34}$ if k_i is given in one coord system. $\frac{\partial g_{ij}}{\partial x^i}$ & then α'_i are found by coord transf. then k'_i can be

Max. of 10 Killing fields can be found in space

$$10 = 4 \text{ Transl.} + 3 \text{ Boost} + 3 \text{ Rotation}$$

Prove

1) In a symmetric space for an affinely parameterized geodesic $U^i K_i = \text{constant}$ along the geodesic & along the cross curves

2) Just as in lag. mechanics by the symmetries of space conservation of q comes, similarly in GR by Killing fields, conservation of q comes.

$$U^i K_i^{(t)} = \text{const} = \tilde{E} = E/m; \quad U^i K_i = \text{const} = \tilde{L} = L/m$$

3) $\tilde{E} = \text{Killing Energy} = U^i K_i^{(t)}$

no. space

flat

$\nabla_a T^a_b = 0$
 $\pi_i = \int d^3x T_{0i} = \text{const}$
 $\nabla_a T^{ab} = 0$

$\int K_i \left(\int d^3x T_{0i} \right) d^4x \Rightarrow P^i = \int \sqrt{-g} d^3x T_{0i} = \text{const}$
 $U^i = \text{const}$ lets choose coord. where $K_i = (1, 0, 0, 0)$

4) that coord. frame $U^0 \cong \text{const}$.

going to flat spacetime in that coord. frame $\frac{dt}{dr} \cong r \cong \text{const}$

as $U^0 \cong \text{constant}$ in that coord. frame it will remain const. in any other coord. frame also

5) \tilde{E} : go to ∞ to calculate \tilde{E} ; can be +/-
 $E_{\text{local}} = U_{\text{obs}}^i U_{\text{part.}}^i$; E_{local} is the Energy measured when we go there.

Justification: go to the observer frame

$$U_{\text{obs}}^i = (1, 0, 0, 0)$$

$$\therefore \tilde{E}_{\text{local}} = U_{\text{particle}} = \frac{E_{\text{local}}}{m}$$

as $\vec{P}_q = (E, \vec{p})$

6) Prove: For any 2 congruence of curves U^i, K^i
 $\alpha_U K^i = -\alpha_K U^i = 0$
& if those curves are affinely param. geod.
 $\Rightarrow U^i K_i = \text{const.} \Rightarrow U^i K_i = 0$

(40) $DA^\alpha = 0$ is 1st order DE which is always solvable

(41) \therefore It needs one Initial condⁿ.
 \therefore Along ~~the~~ ~~geod.~~ any curve A^α is // Transported

(41) for flat spacetime $\frac{dA^\alpha}{d\lambda} = 0$ ~~coord~~ ^{component}, not def. on coord

\therefore $k^t(x)$ along any curve will be same \Leftrightarrow Unique solⁿ

\therefore vector comes back to itself after round.

We know for flat spacetime solⁿ \exists

(42) Condⁿ to give Unique solⁿ $\partial_i A^\alpha + \Gamma_{i\epsilon}^\alpha A^\epsilon = 0$
 $(\partial_m \partial_i - \partial_i \partial_m) A^\alpha = -R_{pmi}^\alpha A^p$

for flat spacetime $\Rightarrow R_{pmi}^\alpha = 0$

$i, m \equiv$ spacetime index
 $\alpha, p \equiv$ internal spacetime

If the solⁿ \exists for $\Gamma \neq 0$ then for that spacetime $R_{pmi}^\alpha \neq 0$

(43) Prove
 The solⁿ of $\partial_i A^\alpha + \Gamma_{i\epsilon}^\alpha A^\epsilon = 0$ as $\Delta v^\alpha = -\frac{R_{bcd}^\alpha}{2} v^b v^c dx^d$ doesn't \exists for $\Gamma \neq 0$

(Proof?)

(44) $(\nabla_i \nabla_j - \nabla_j \nabla_i) v^k = -R_{mij}^k v^m$

(45) $(\nabla_i \nabla_j - \nabla_j \nabla_i) v_k = R_{kij}^m v_m \Rightarrow R_{kij}^m$ is Tensor

(4) Geodesic Deviation:

47) Newtonian limit.

48) What is the Difference B/w Local I.f. & □ Box falling freely?
 49) Properties of R^a_{bcd} c, d : spacetime index
 a, b : internal spacetime index

$R_{abcd} = -R_{bacd}$
 $R_{abcd} = -R_{abdc}$
 $R_{abcd} = R_{cdab}$
 $R_{a[bcd]} = 0$

Why Properties in L.I.f. will remain true in general?

$X = R_{a[bcd]}$ is A.S. in any of its indices.

- 50) What are the no. of Ind. components of R^a_{bcd} ?
 Why No. of nonzero nonvanishing $\partial_i \partial_j g_{ab}$ enters R^a_{bcd} ?
 51) Why 1 & 3rd comp. being contracted?
 52) To prove Ricci Tensor is symmetric?
 To prove Einstein Tensor is sym?

53) Bianchi Identity

Prove: $\nabla_{[i} R^a_{bcd]} = 0$

54) To prove Divergence of Einstein Tensor = 0.

55) AS $R_{\beta\gamma\delta} = \partial_i \Gamma^\alpha_{\beta\gamma} \partial_i \delta^\alpha_\delta \phi$

& Newton's Approx $\nabla^2 \phi = 4\pi G \rho \therefore R^{\alpha}_{\beta\gamma\delta}$ should be there in field eqn

56) Assumption: All laws can be generalized from flat spacetime to curved.

Eg. $\int \sqrt{g} g_{ij} dx^i dx^j \rightarrow$ in acc. frame $g_{ij} = e^{\alpha\beta} \rightarrow ds^2 = g_{ij} dx^i dx^j$
 $\int F_{ab} dx^a dx^b \rightarrow$ in acc. frame $F_{ab} F^{ab} \rightarrow F_{ab} F^{ab}$
 Principle of Equivalence.

57) The above procedure is not unique. Explicit coupling to curvature can be there. Eg. $L_m + R$ as $R=0$ in L.I.f.
 Coupling to curvature can't be determined by Eq. princip.

58) $A = \int L_1 \sqrt{-g} d^4x + \int L_2 \sqrt{-g} d^4x$
 Matter \downarrow for gravity field

$\delta A_m = \int T_{ab} \delta g^{ab} \sqrt{-g} d^4x$ $\delta A_g = \int -E_{ab} \delta g^{ab} \sqrt{-g} d^4x$

Tab is Symmet. Tensor.

(59) Tab is internally there in GR unlike scalar & EM field

(60) Prove $\nabla_a T^{ab} = 0 \iff$ EOM

(61) For Many particles $T_{ab} = \rho U^a U^b$ (Dust)

↓
Pressureless

(62) For Ideal fluid

Prove: $T_{ab} = (\rho + p) U^a U^b - p g^{ab}$

Radiation is the ideal fluid.

(63) $T_b^a = \rho U^a U_b - p (\delta_b^a - U^a U_b)$

$P_b^a =$ Projection Operator

$P_b^a U^b = 0$

(64) $T_b^a = \rho U^a U_b - p P_b^a$

in rest frame $U^b = (1, 0, 0, 0) \Rightarrow P_b^a \in$ spacelike

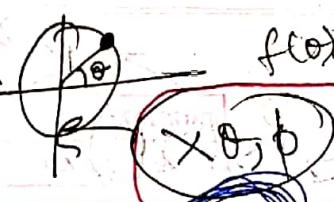
\therefore pressure acts on space

(5) $T_a^a = (\rho + p) - \delta_a^a p = \rho - 3p$

for ideal fluid $p = \frac{\rho}{3} \therefore T_a^a = 0$

(66)

isolate one pt. with other on sphere



flavor why? similar for $\beta(\theta, \phi)$
 introduce $\alpha, \mu(r, t)$
 $r(r, t)$
 $dt dr d\theta d\phi$

PAGE NO. 20

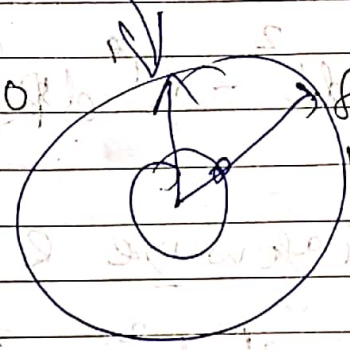
① $ds^2 = \alpha dt^2 - \beta dr^2 - r^2(d\Omega^2) - \mu dr dt$
 spherical symmetric = at $r=0$ it should look like surface sphere.

find killing vectors describing spher. symmetry

① $g_{\alpha\beta}$ given

$\nabla_{\alpha} k_{\beta} = 0$
 some

find k_{β}



② Here k_{β} given

find $g_{\alpha\beta}$ which will obey $\nabla_{\alpha} k_{\beta} = 0$

Why can't we have $dr d\theta, dr d\phi$

② if $\alpha \neq \beta(r, t)$
 $\alpha(\theta, \phi)$ then dynamical eqn depend on which Angular coordinate you're choosing

③ Th. Any quad. form in 2 variable can be diag.
 $\therefore dr dt = 0$

④ \therefore Only by sph. sym.
 $ds^2 = \alpha dt^2 - \beta dr^2 - r^2 d\Omega^2$

$\alpha, \beta, r(r, t)$

Doubt

$(t, r, \theta, \phi) \rightarrow (t', r, \theta, \phi)$ $t \rightarrow t'$

$dt' = A dt + B dr$
 $(dt')^2 = A^2 dt^2 + B^2 dr^2 + 2AB dt dr$

where $A^2 = \alpha$
 $2AB = \mu$
 $B^2 = \beta$

$r \rightarrow R$
 $(t, r, \theta) \rightarrow (t, R, \theta)$

PAGE NO.:
 DATE: / / 20

$(5) ds^2 = \alpha dt^2 - \beta dr^2 = \gamma (dR^2)$

~~R^2~~ ~~r^2~~ $r^2 = r(r, t)$
 ~~dr~~

$2dR = \frac{\partial R}{\partial r} dr + \frac{\partial R}{\partial t} dt$

$ds^2 = \alpha \alpha' dt^2 - \beta' dR^2 - R^2 dr^2 - f dr dt$

Again Diagonalize & let $R = r$

$ds^2 = \alpha' dt^2 - \beta' dr^2 - r^2 dr^2$

$(6) A = \int ds$ or ~~$A = \int$~~

$= \int \sqrt{\alpha' dt^2 - \dots}$

$= \int \frac{\dots}{dt} dt$

$= \int \sqrt{\alpha' - \beta' \frac{dr^2}{dt^2} - r^2 \frac{dr^2}{dt^2}} dt$

$= \int L dt \quad \} \rightarrow A = \int L^2 dx$

$L' = L = \alpha' \left(\frac{dt}{dx}\right)^2 - \beta' \frac{dr^2}{dx^2} - r^2 \frac{dr^2}{dx^2}$
 $\alpha', \beta'(r, t)$

x is affine

find Γ, R by this

$\frac{d}{dx} \left(\frac{\partial L'}{\partial \dot{x}} \right) = \frac{\partial L'}{\partial x}$

$q = t \rightarrow \frac{d}{dx} \left(\frac{\partial L'(t^2)}{\partial \dot{t}} \right) = \frac{\partial L'}{\partial t}$

Let metric be static

$$\therefore \alpha', \beta' \propto t$$

$$\therefore \frac{\partial L'}{\partial t} = 0$$

$$\therefore \frac{d}{dx} (\alpha' \dot{t}) = 0$$

$i = 0$
 $\Gamma_{tr}^t \neq 0$
all other zero

$$2 \alpha' \ddot{t} + 2 \dot{t} \frac{\partial \alpha'}{\partial r} \dot{r} = 0$$

$$\Rightarrow \left(\dot{t} + \frac{\partial \alpha'}{\partial r} \dot{r} \right) \dot{r} = 0 \rightarrow \frac{d^2 x^i}{dx^2} + \Gamma_{\mu\nu}^i U^\mu U^\nu = 0$$

Similarly

$$q = r \quad \frac{d}{dx} (-\beta' \dot{r}) = \frac{\partial}{\partial r} (\alpha' \dot{t}^2 - \beta' \dot{r}^2 - \gamma \dot{r}^2)$$

$$q = \theta, \phi$$

Assuming no staticity of α, β (r, t)
we get by EFE these 2 eqn

⑦ $\beta = 0$

using EFE in vacuum $\Rightarrow G_{ik} = 0$

$$r \frac{\alpha'}{\alpha} + (1 - \beta) = 0$$

$$r \frac{\beta'}{\beta} - (1 - \beta) = 0$$

$$g^{\alpha\beta} R_{\alpha\beta} = 0 \quad \alpha' \beta' - \beta' \alpha = 0$$

$$\frac{\partial (\alpha\beta)}{\partial r} = 0$$

$$\alpha\beta = q(t)$$

$$\alpha(t, r) = \frac{q(t)}{\beta(t, r)} = \frac{q(t)}{\beta(r)}$$

(time dep. & spatial dep. separable it out)

$$\frac{\partial \beta(r, t)}{\partial t} = 0 \quad \therefore \beta(r)$$

$$(8) ds^2 = \frac{g(t) dt^2}{\beta(r)} - \beta(r) dr^2 - \dots$$

$$dt' = \sqrt{g(t)} dt$$

$$\therefore ds^2 = \frac{dt'^2}{\beta(r)} - \beta(r) dr^2 - \dots$$

$$\therefore g(t) = 1$$

$$\therefore \alpha(t, r) = \frac{1}{\beta(r)}$$

$$\therefore \alpha(t, r) = \alpha(r)$$

$$\alpha = \frac{1}{\beta}$$

$$(9) \frac{r}{\alpha} \alpha' + \left(1 - \frac{1}{\alpha}\right) = 0$$

$$r\alpha' + (\alpha - 1) = 0$$

$$\int \frac{d\alpha}{\alpha - 1} = - \int \frac{dr}{r} = \ln\left(\frac{c}{r}\right) = \ln(\alpha - 1)$$

$$c = r(\alpha - 1)$$

$$\alpha = 1 + \frac{c}{r}$$

$$\beta = \frac{1}{\alpha}$$

$$(16) ds^2 = \left(1 - \frac{c}{r}\right) dt^2 - \frac{dr^2}{\left(1 - \frac{c}{r}\right)} - r^2 d\Omega^2$$

weak far away

$$g_{00} = 1 - 2\phi$$

$$\phi = -\frac{GM}{r}$$

Assume we are looking from outside $r > r_s$

Problem of a horizon

We have not assumed anything about body is static. But the metric outside would still be static

$$r \gg 0$$

$$ds^2 \approx dt^2 - dr^2 - r^2 d\Omega^2$$

$$ds^2 = g_{00} dt^2 - g_{ij} dx^i dx^j$$

in polar coord

$$ds^2 = g_{00} dt^2 - dr^2 - r^2 d\Omega^2$$

$$ds^2 = \left(1 - \frac{c}{r}\right) dt^2 - \frac{dr^2}{\left(1 - \frac{c}{r}\right)} - r^2 d\Omega^2$$

$$c = 2GM = r_s$$

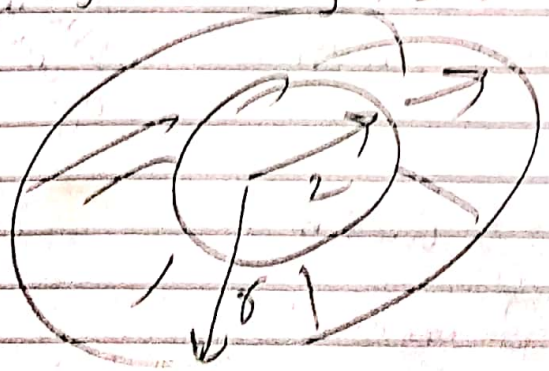
But for deriving this we assumed $r \gg r_s$

L is radius of body

But if $r = r_s$

& $r_s > L$

then there is problem



But let assume

∴ No problem $L > r_s$

Birkhoff's theorem

(11) Source can be Time Dep. in Sph. Symmetry
collapsing in Sph. Symm



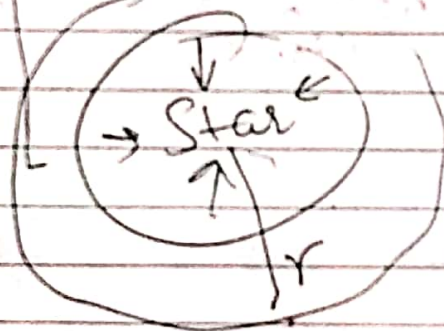
Metric outside it is still Static

Any system which follows EFE vacuum & Syst is spherically Sym.

(12) Newton

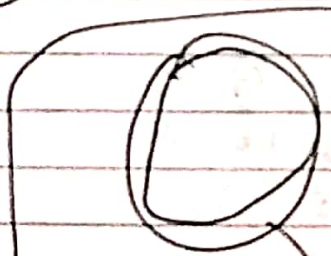
Equal

Gauss theorem



take 2 of star - r

(13) Shell



outside same metric with $c = 2GM$

inside same metric

But different c

Now assuming the given 10^2

wee at $r=0$

Metric is not valid coz we have found it for outside

But here $r=0$ metric should hold

~~as $EFE = 0$ vacuum~~

$\therefore c = 0$

as $EFE \neq 0$ vacuum

(4) But if $c = 0$

flat spacetime

∴ inside shell no grav. field

∴ No Curvature

In Newtonian theory
in shell sphere

$\phi = \text{constant}$ inside

in shell Ellipsoid / weird config

$\phi = \text{const.}$ inside

But in GR
only for
spherical
sym. case
 $\phi = \text{const.}$

(15)

L-18

Suppose this is the metric given

$$(1) ds^2 = f(r) dt^2 - f^{-1}(r) dr^2 - r^2 d\Omega^2$$

put it in EFE

Calculate LHS \rightarrow get T_{ab}

if T_{ab} is this then we have a solution by EFE

By EFE we get

$$(2) T^t_t = T^r_r = \frac{\epsilon(r)}{8\pi G} \rightarrow \text{let } T^t_t = \frac{\epsilon}{8\pi G}$$

~~By EFE we get~~

By EFE we get 2 eqn

$$\frac{1}{r^2} (1-f) - \frac{f'}{f} = \epsilon \quad (1)$$

$$\mu = \epsilon + \frac{2\epsilon'}{r} \quad (2)$$

$$T^t_t = T^r_r = \frac{\mu(r)}{8\pi G}$$

let $T^t_t = \frac{\mu}{8\pi G}$

Given any ϵ , find f , and find μ

PAGE NO.:

DATE: / / 20

② Solving ①

$$f = 1 - \frac{a}{r} - \frac{1}{r} \int_a^r \epsilon r^2 dr \quad \text{--- (2)}$$

a is Int. const s.t. $a=r \Rightarrow f=0$

Now let $\epsilon=0$ Empty space solⁿ

If $\epsilon=0$ then by ② $\mu=0$

$\therefore T_{\beta}^{\alpha} = 0$ Empty space

In ③ if $\epsilon=0$

$$\rightarrow f = 1 - \frac{a}{r}$$

$$\equiv 1 - \frac{2GM}{r}$$

$$\frac{1-f}{r^2} - f' = \epsilon(r)$$

$$1-f - f'r = \epsilon r^2$$

$$1 - \epsilon r^2 = f + f'r$$

$$r - \epsilon r^2 = \frac{d}{dr}(fr)$$

$$\int_a^r (1 - \epsilon r^2) dr = fr$$

$$\frac{1}{r} \left[(r-a) - \int_a^r \epsilon r^2 dr \right] = f$$

$$1 - \frac{a}{r} - \int_a^r \epsilon r^2 dr = f$$

④ a constant is chosen in such a way that when $a = r$ $f = 0$ we could have chosen it in any other way.

⑤ $f = 1 - \frac{a}{r} + \frac{1}{r} \int \epsilon r^2 dr$

$\epsilon = 0$ (Empty space)
 $f = 1 - \frac{a}{r}$

∴ consistent

⑥ let $\epsilon = \text{const}$
then $\mu = \epsilon$
∴ $T^i_j = \text{const}$

But earlier when $L =$

$(+k)$

to a scalar field
 $T^i_j = H = \pi^i_j \phi - \delta^i_j L$

Constant ϵ of $T^a_b = \delta^a_b k$

Equivalent

⑦ Now let $\epsilon = \text{const}$
Solution to

$f = 1 - \frac{a}{r} + \int_a^r \epsilon r^2 dr$

Assume No mass ∴ $T^a_b = 0$ ∴ $\epsilon = 0$

just T^a_b due to const ϵ is there

$a = GM$ & ϵ is there due to const

and $M = 0$ ∴ $a = 0$

$\Rightarrow f = 1 - \frac{\epsilon r^2}{3} = 1 - H^2 r^2$

De Sitter Universe

de Sitter Universe
 ↳ when only const is ~~added~~ \log
 DATE: / / 20

⑧ $ds^2 = (1 - H^2 r^2) dt^2 - \frac{dr^2}{1 - H^2 r^2} - r^2 d\Omega^2$

⑨ Till now we studied mass particle at origin
 now
 lets have charge particle

$E = \frac{q}{r^2}$

Energy Density = $\frac{E^2}{8\pi} \Rightarrow \frac{q^2}{r^4}$

$E = \frac{q}{r^2} \Rightarrow f = 1 - \frac{a}{r} + \frac{q}{r^2}$

let $a = 2GM$ (from previous)

for charged particle

$f = 1 - \frac{2GM}{r} + \frac{q}{r^2}$

↳ $ds^2 = \left(1 - \frac{2GM}{r} + \frac{q}{r^2}\right) dt^2 - \frac{dr^2}{\left(1 - \frac{2GM}{r} + \frac{q}{r^2}\right)} - r^2 d\Omega^2$

(RN) Reissner Metric for Electrostatic

we can also prove it on general grounds as we have proved for Sch. metric

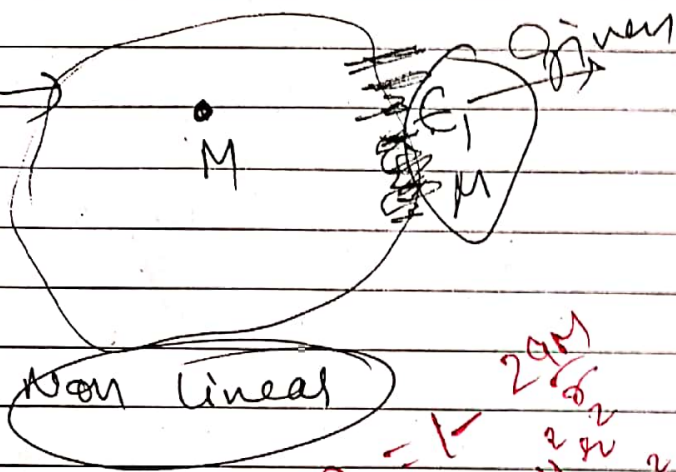
⑩ EFE is Non linear $\Rightarrow R_{ij} = T_{ij}$

But $\frac{1}{r^2} (1-f) - \frac{f}{r^2} = E \quad T = (2_{ij}g) : (2_{ij}g)^2 \rightarrow$ linear inf

∴ Superposition ⇒ ∴ 2 sources ϵ_1 & ϵ_2
 $\epsilon_1 + \epsilon_2$

Linear Eqn

$$a_0(x)y + a_1(x)y' + a_2y'' \dots a_ny^n + b(x) = c$$



$$\frac{1-f_g}{r^2} - \frac{f_g'}{r} = \epsilon_g$$

$$\frac{1-f_d}{r^2} - \frac{f_d'}{r} = \epsilon_d$$

Red annotations:

$$f_a = 1 - \frac{2qm}{r^2}$$

$$f_d = 1 - \frac{4qm}{r^2}$$

$$F = 2 - \frac{4qm}{r^2}$$

$$\frac{2-F}{r^2} - \frac{F'}{r} = E$$

$$\text{Sol } Q + \text{Sol } D = \text{Sol } E$$

(11) $f\ddot{q}_1 + g\dot{q}_1 + h_1 = 0$ L_q

$f, g, h (q, \dot{q}, t)$

$f_1\ddot{q}_2 + g_1\dot{q}_2 + h_1 = 0$ L_{en}

$f\ddot{q} + g\dot{q} + h = 0$

Newtonian eq
a linear eq

Interact $d \neq L_m + d_g$ ↗

Alex Hourney

L15

PAGE NO.:

DATE:

metric of Compact Star

① In this metric \rightarrow

$$ds^2 = f(r) dt^2 - f^{-1} dr^2 - r^2 d\Omega^2$$

g_{ij} ind. of (t, ϕ)

$$\therefore \left. \begin{matrix} k^\mu u_\mu = E \\ k_\phi u^\mu = L \end{matrix} \right\} \text{const} \Rightarrow \begin{matrix} L = \text{const} \Rightarrow \text{particle} \\ \text{motion around} \\ \text{star in a plane.} \end{matrix}$$

\rightarrow As its ind. of (t, ϕ) ; $\frac{dU_i}{ds} = \frac{\partial g_{ij}}{\partial x^k} U^j U^k$

U_0 is constant \downarrow

for Both Photon & material particle

$$U_0 = g_{00} U^0 = g_{00} \frac{dt}{ds} = \text{const} = k$$

②

$$\boxed{\frac{dt}{ds} = \frac{k}{g_{00}}}$$

now doing this for $k^\mu u_\mu = E$

Let Coordinate Basis be killing vectors in that frame also $k^\mu u_\mu = \text{const}$ would be valid

But $k^\mu \neq (1, 0, 0, 0)$

$$\therefore U_0 = g_{00} U^0 = g_{00} \frac{dt}{ds} = E$$

③

$U_{obs}^\mu p_i = \text{Energy of photon}$

$(U_{obs}^\mu p_i)_i = \text{Observer located at } \text{cpt}$

$$(u_i p^i) = E = h\nu$$

~~(u_i p^i)~~

$$\frac{(u_i p^i)_1}{(u_i p^i)_2} = \frac{\omega_1}{\omega_2} \rightarrow \text{freq. of photon} \quad (1)$$

Only for static metric

(3) $u^i_{obs} \equiv \frac{1}{N(\vec{x})} (1, 0, 0, 0)$ (Defn)

↑
spatial \rightarrow for static metric

This guy is sitting quietly

\therefore His spatial velocity should vanish

$$u^i u_i = 1 \Rightarrow g_{00} \frac{1}{N^2} = 1 \Rightarrow N^2 = g_{00}$$

in SR $\omega_1 = \omega_2$
as c is const for all frame
in (1)

Same as $u_0^i u_i$
const

Lapse

here freq. changes

$$\frac{p_0}{N_1} = \frac{p_0}{N_2} = \frac{N_2}{N_1} = \frac{\omega_1}{\omega_2}$$

where $N_1 = N(\vec{x}_1)$
↑
Spatial vecto

p_0 is conserved as $\frac{d u^i}{d x^2} = \frac{d g_{\alpha\beta}}{d x^2} u^\alpha u^\beta$
 p_0 is same $(1, 0, 0, 0)$
Diff is of N_1 & N_2 at Diff places of Observer

$N_2 = N(\vec{x}_2)$
↑
Spac

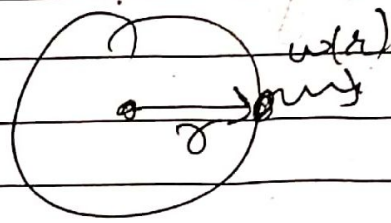
But u^2, u^3 are not const
 $u^4_{photon} = \text{const}$

(4) $\omega_\infty = \omega(r) \frac{N_\infty(r)}{N(r)}$ $N(\infty) = 1$

$$\omega_\infty = \omega(r) \left(1 - \frac{2GM}{r}\right)^{1/2}$$

∴ frequency of photon changes

if freq is $\omega(r)$ at



$\omega(r)$

as r reaches $r_s = 2GM$

$\omega \downarrow \downarrow$ ∴ Red shift.

Examples

in Schwarzschild geometry $g_{tt}(r) = 1 - \frac{2GM}{r}$

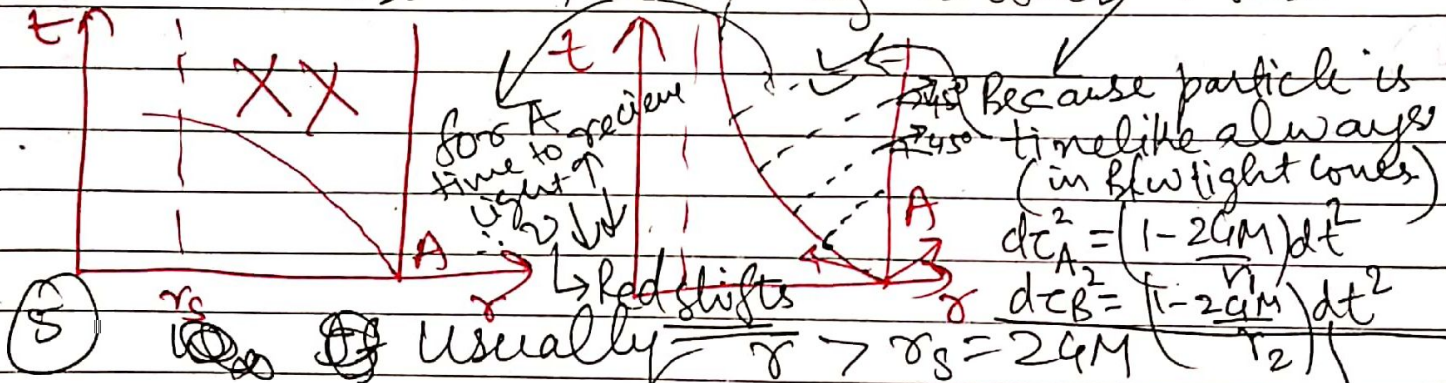
Photon

$\frac{dt}{dr} = \pm \left(1 - \frac{2GM}{r}\right)^{-1}$

in Sch. coord

Every photon going asymptotically

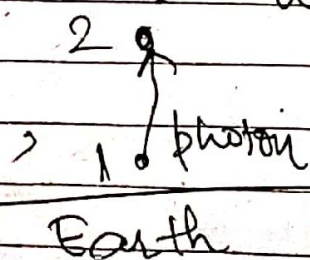
Now let 2 Observers, one moving & other at Rest



$\left(1 - \frac{2GM}{r}\right) < 1$

$\frac{d\tau_A}{d\tau_B} = \sqrt{\frac{1 - \frac{2GM}{r_2}}{1 - \frac{2GM}{r}}}$

$\omega \downarrow \downarrow \Rightarrow \omega_2 < \omega_1$



the freq of photon at 2 is less than 1

∴ Energy of photon dec.

In lecture (7)

Bring/Derive that Result from this

(6) Even with cosmological loss, you can have complete static metric.

(7)